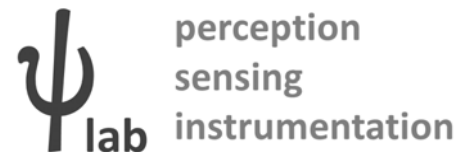


# Active analysis of chemical mixtures with multi-modal non-negative least squares

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# Overview

## Introduction

- What is active sensing?
- Infrared Fabry-Perot interferometry

## Methods

- Non-negative least squares
- Multi-modal search
- Wavelength selection

## Results

- Chemical dataset
- System behavior
- Comparison with passive sensing

## Discussion



# What is active sensing?

## Perception is an active process

– “We not only see but we look, we not only touch we feel”

-J.J. Gibson

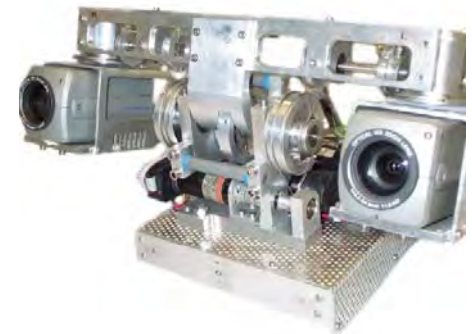
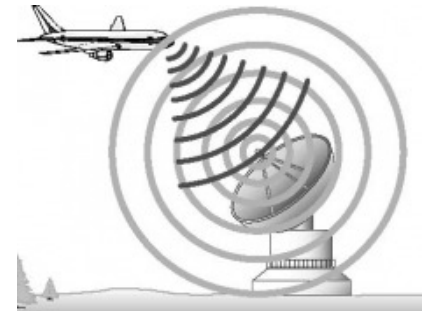
## Active sensor vs. active sensing

– **Active sensor:** a device that transmits energy in order to make measurements

- E.g., radar, sonar

– **Active sensing:** a control strategy that dynamically adapts the sensor’s configuration as it interacts with the environments

- E.g., changing camera viewpoints



# What is active sensing?

## Analogy

### – Guessing games

- 20 questions, Pictionary, Battleship, Yes and no, Hangman

Question	Answer
Is your character real?	Yes
Is your character male?	Yes
Is he alive?	Yes
Is he an actor?	No
Is he linked with sports?	No
Is he a musician?	Yes
Is he more than 50 years old?	Yes
Does he play the guitar?	Yes
Is he American?	Yes
Does he wear headgear?	Yes
Does he have messy hair?	Yes
Is it Bob Dylan?	Yes

Vague



Specific

# What is active sensing?

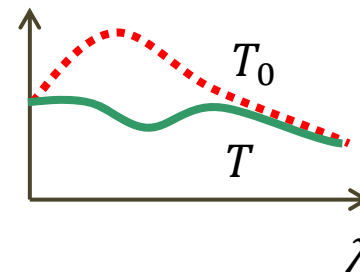
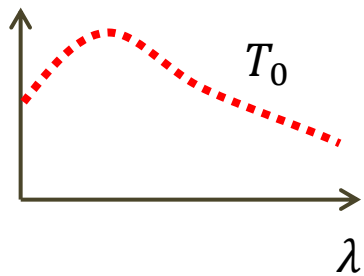
## Analogy

- Guessing games
  - 20 questions, Pictionary, Battleship, Yes and no, Hangman
- Two seemingly conflicting problems at the same time
  - Find the right answer
  - Ask the right questions
- Advantage
  - Incorporate decision early in the signal processing pipeline
  - Reduce sensing costs (\$, energy, time, computing power)
  - Lower sensor requirements

# Prior work

Chemical	Identity	Concentration	Sensor	Reference
Single	Unknown	Fixed	MOX	Gosangi et al. 2010 <i>IEEE Sensors J</i>
Single	Unknown	Unknown (continuous)	FPI	Huang et al. 2012 <i>IEEE Sensors J</i>
Mixture	Known	Unknown (discrete)	MOX	Gosangi et al. 2013 <i>S&amp;A B: Chemical</i>
<b>Mixture</b>	<b>Unknown</b>	<b>Unknown (continuous)</b>	<b>FPI</b>	<b>Huang et al. 2013 <i>ICASSP</i></b>

# Infrared absorption spectroscopy

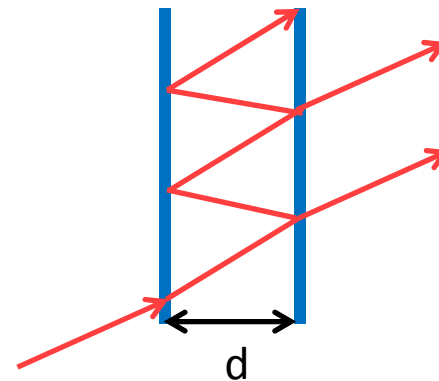


$$A = -\log_{10} \frac{T}{T_0}$$

# Fabry-Perot interferometer



$$A_i = [a_{i\lambda_1}, \dots, a_{i\lambda_n}]^T$$



$$\lambda = f(d)$$

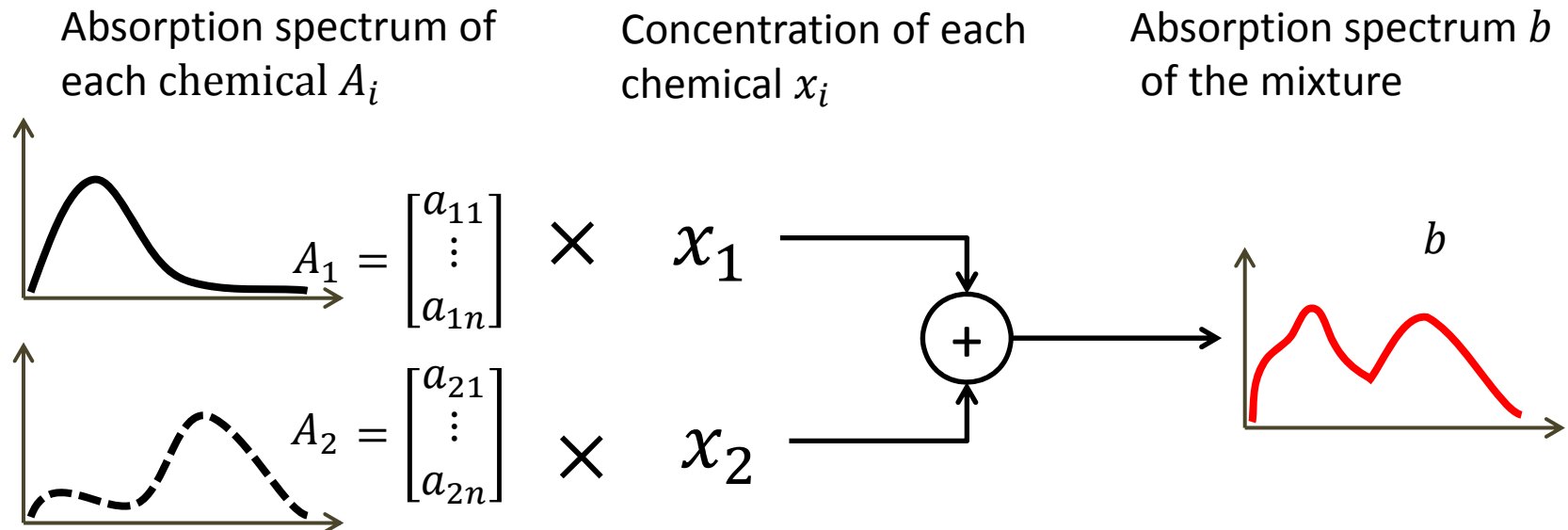


# IR absorption

## Properties

- Absorption spectrum is linear (Beer's law)

$$\sum_{i=1}^p A_i x_i = b$$



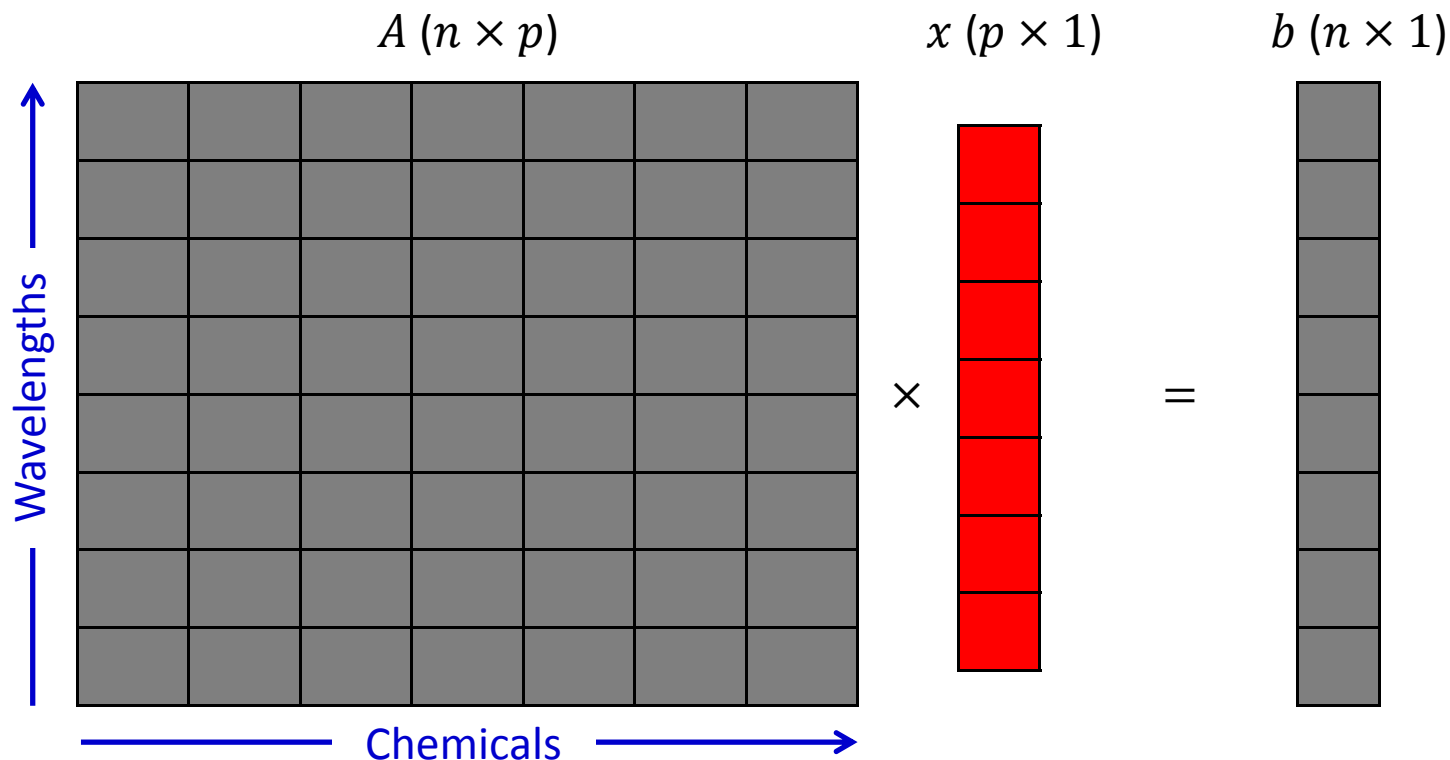
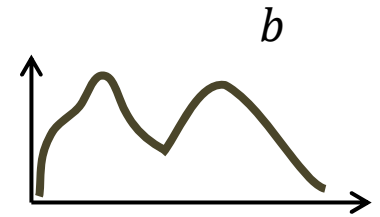
# Traditional mixture analysis

## Problem definition

- Estimate  $x$ , given  $b$  (all wavelengths)



$$Ax = b$$
$$s. t. : x \geq 0$$



# Active mixture analysis

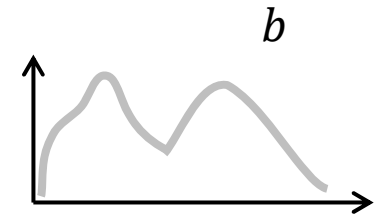
## Problem definition

- Estimate  $x$ , but measuring one wavelength at a time



$$Ax = b$$

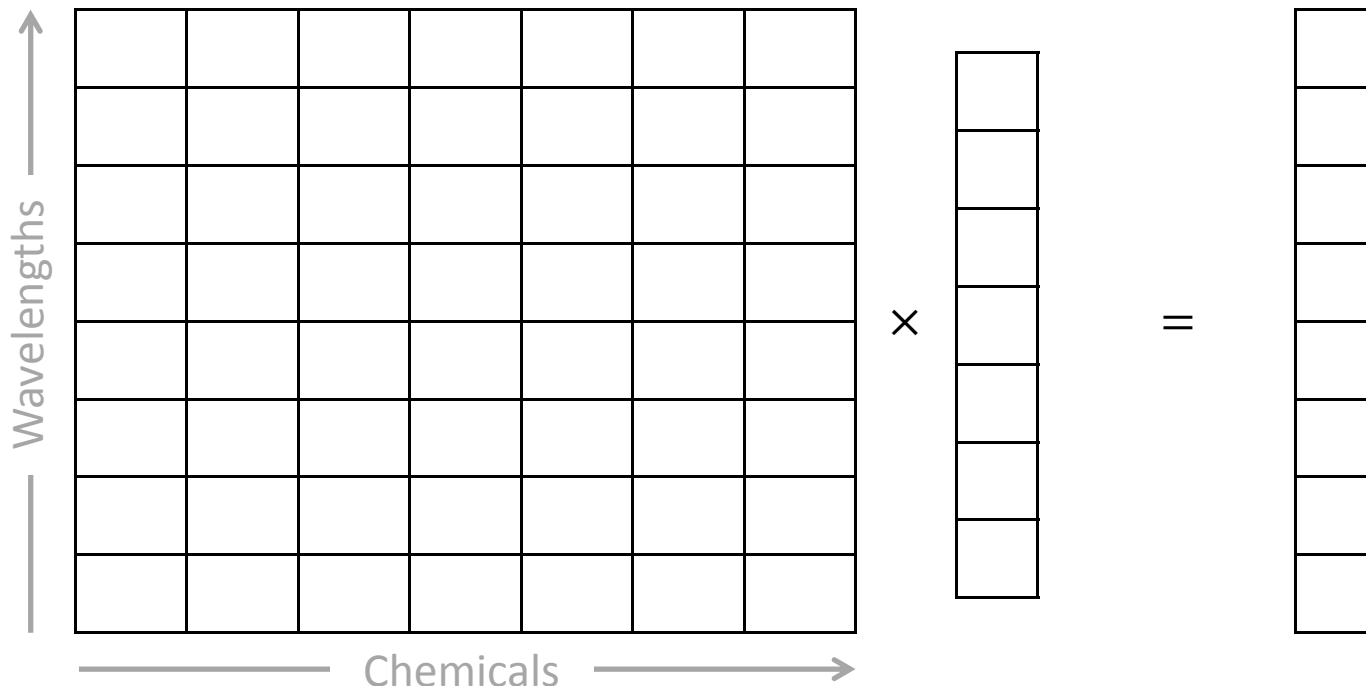
$$s.t.: x \geq 0$$



$A (n \times p)$

$x (p \times 1)$

$b (n \times 1)$



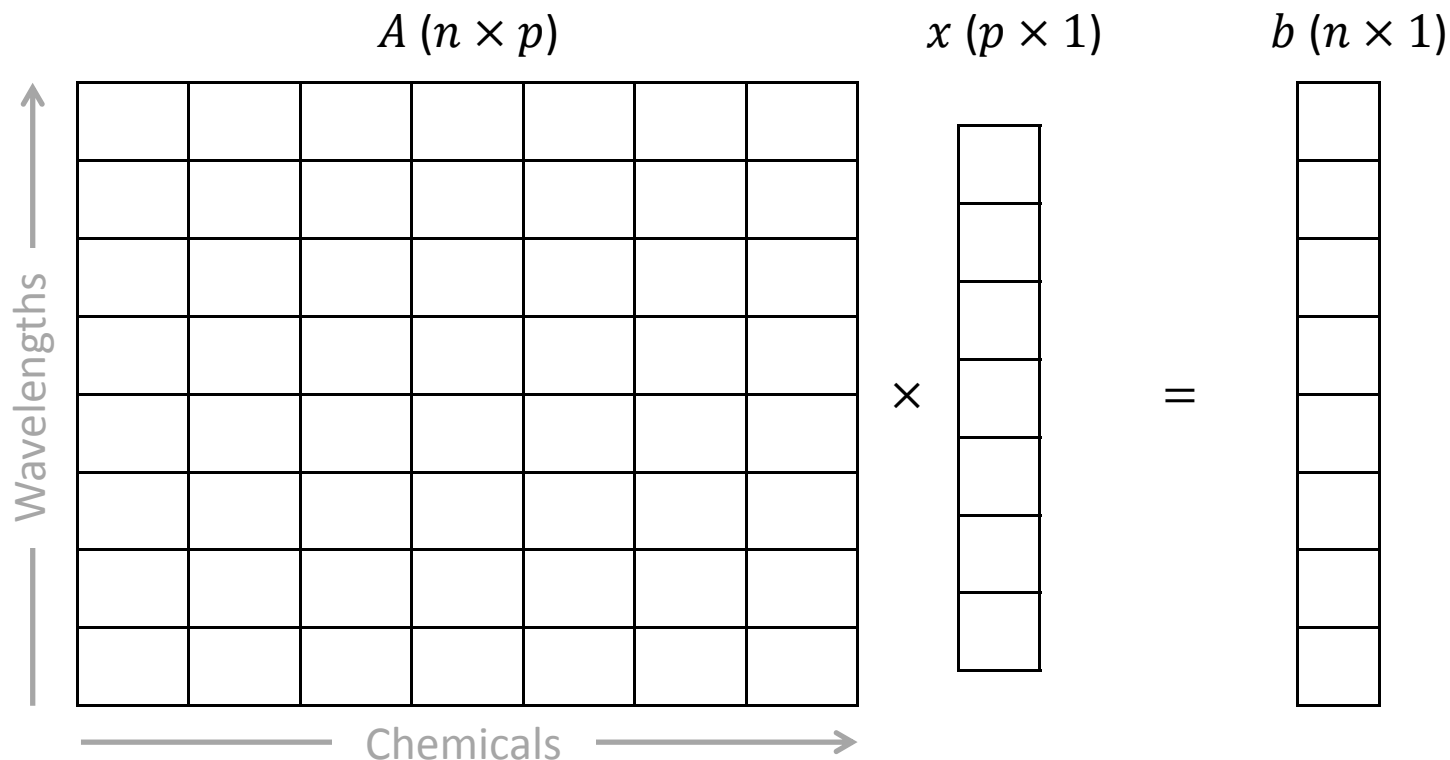
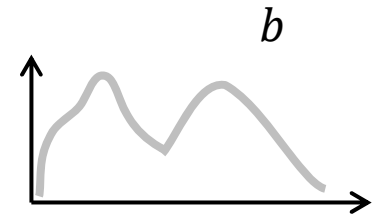
# Active mixture analysis

## Problem definition

- Select the best wavelengths in  $b$  to solve  $Ax = b$



$$Ax = b$$
$$s.t.: x \geq 0$$



# Active mixture analysis

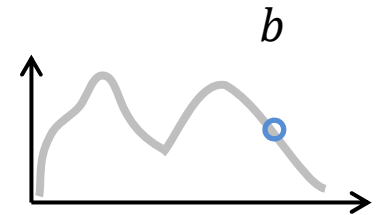
## Interpretation

- Each wavelength equals one element in  $b$



$$Ax = b$$

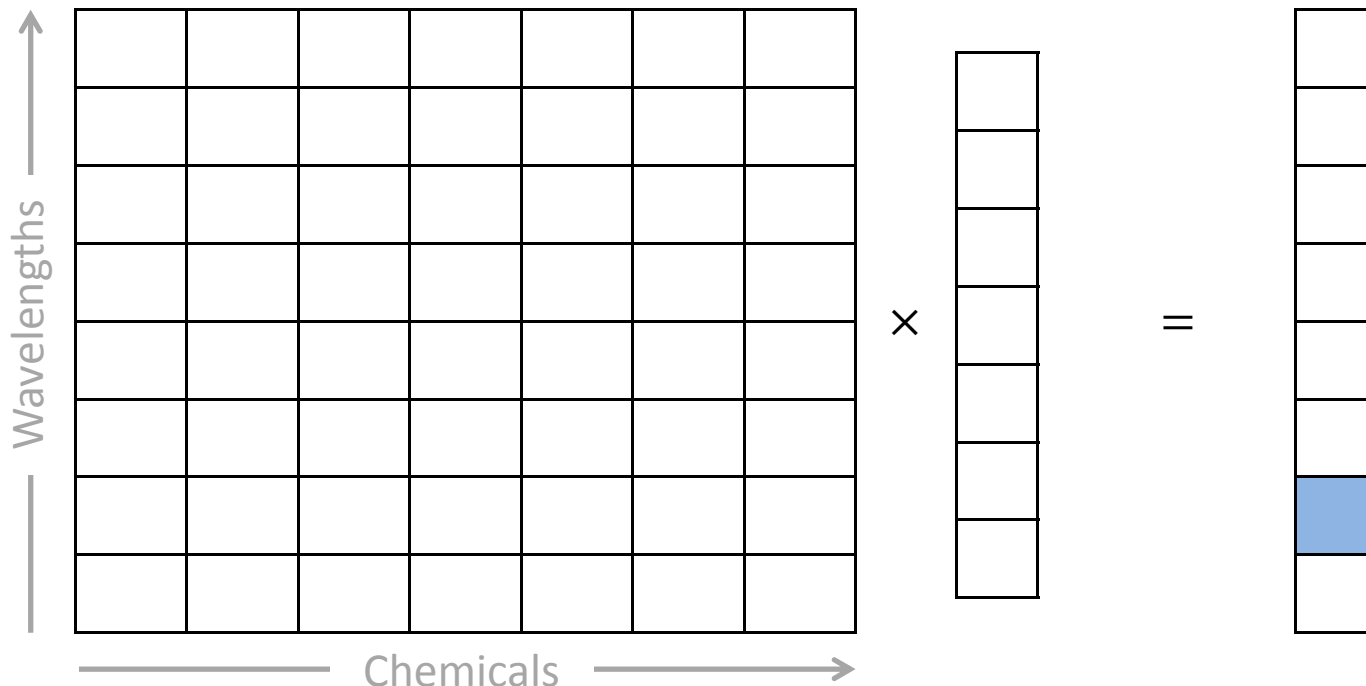
$$s.t.: x \geq 0$$



$A (n \times p)$

$x (p \times 1)$

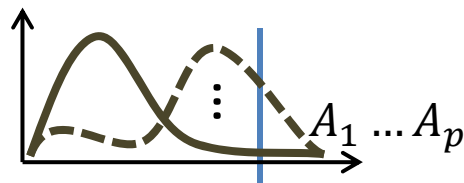
$b (n \times 1)$



# Active mixture analysis

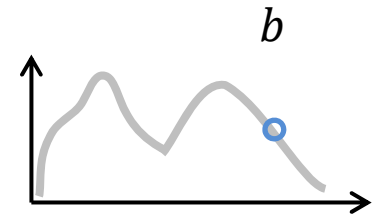
## Interpretation

- Which allows us to use an additional row in  $A$



$$Ax = b$$

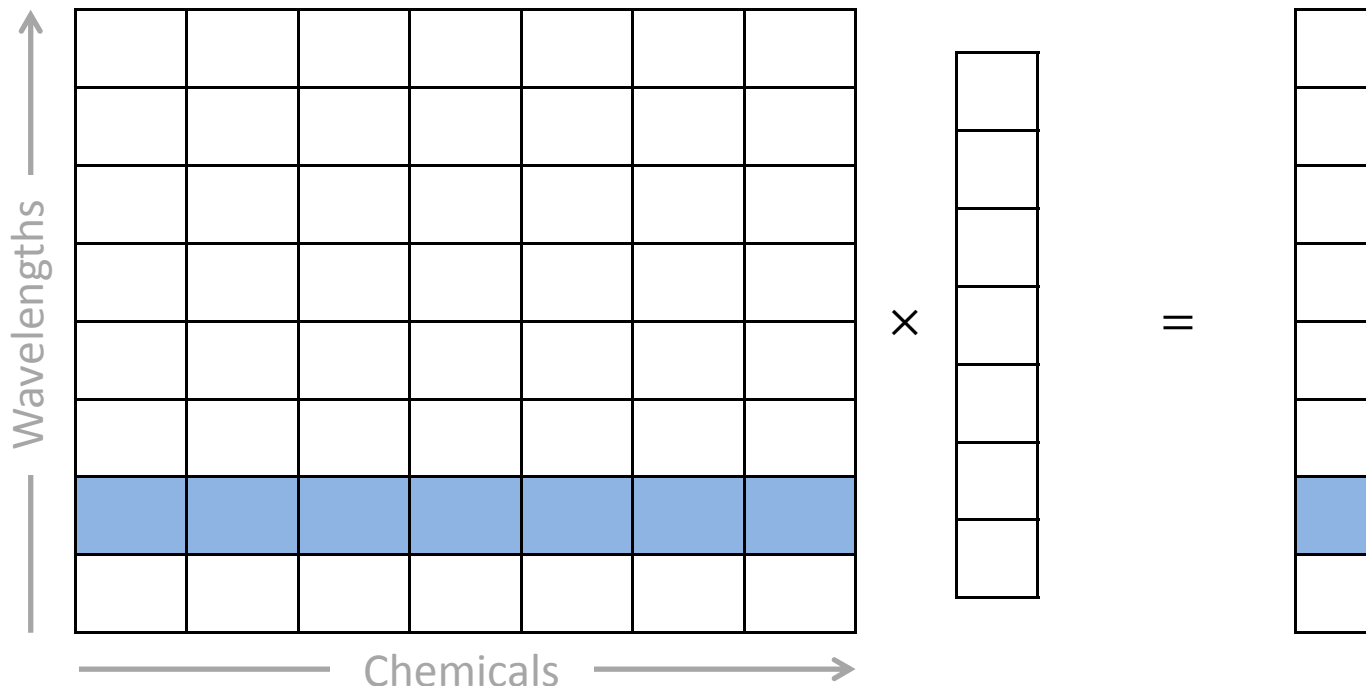
$$s.t.: x \geq 0$$



$A (n \times p)$

$x (p \times 1)$

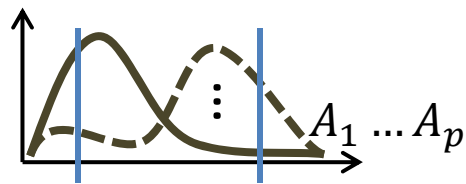
$b (n \times 1)$



# Active mixture analysis

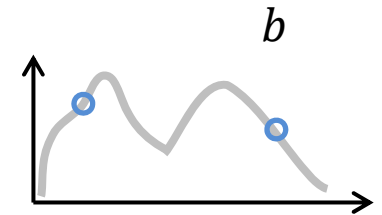
## Interpretation

- Each new wavelength adds a new row in  $A$



$$Ax = b$$

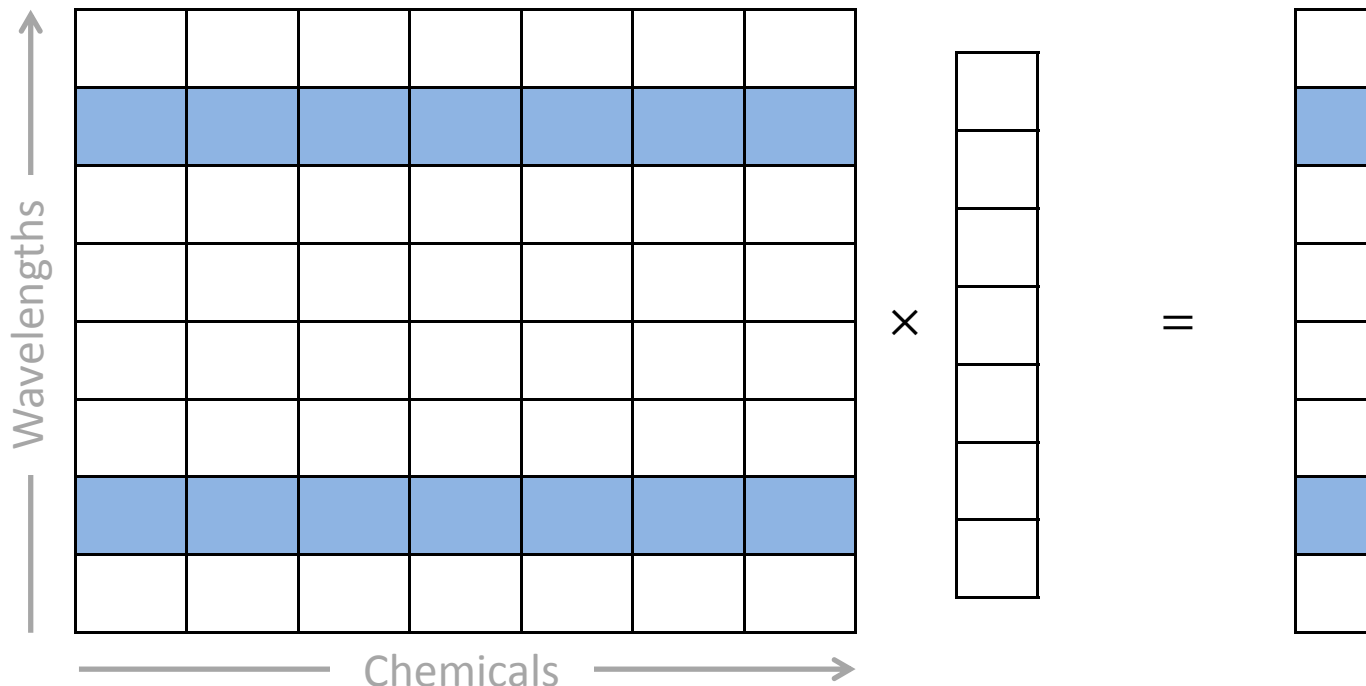
$$s.t.: x \geq 0$$



$A (n \times p)$

$x (p \times 1)$

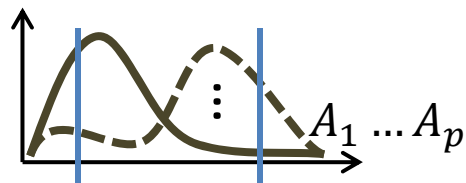
$b (n \times 1)$



# Active mixture analysis

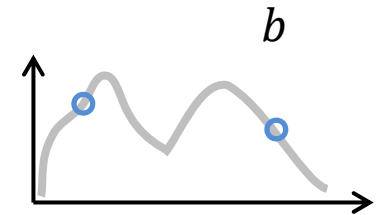
## Issue

- The underlying linear system may be under-determined



$$A'x = b'$$

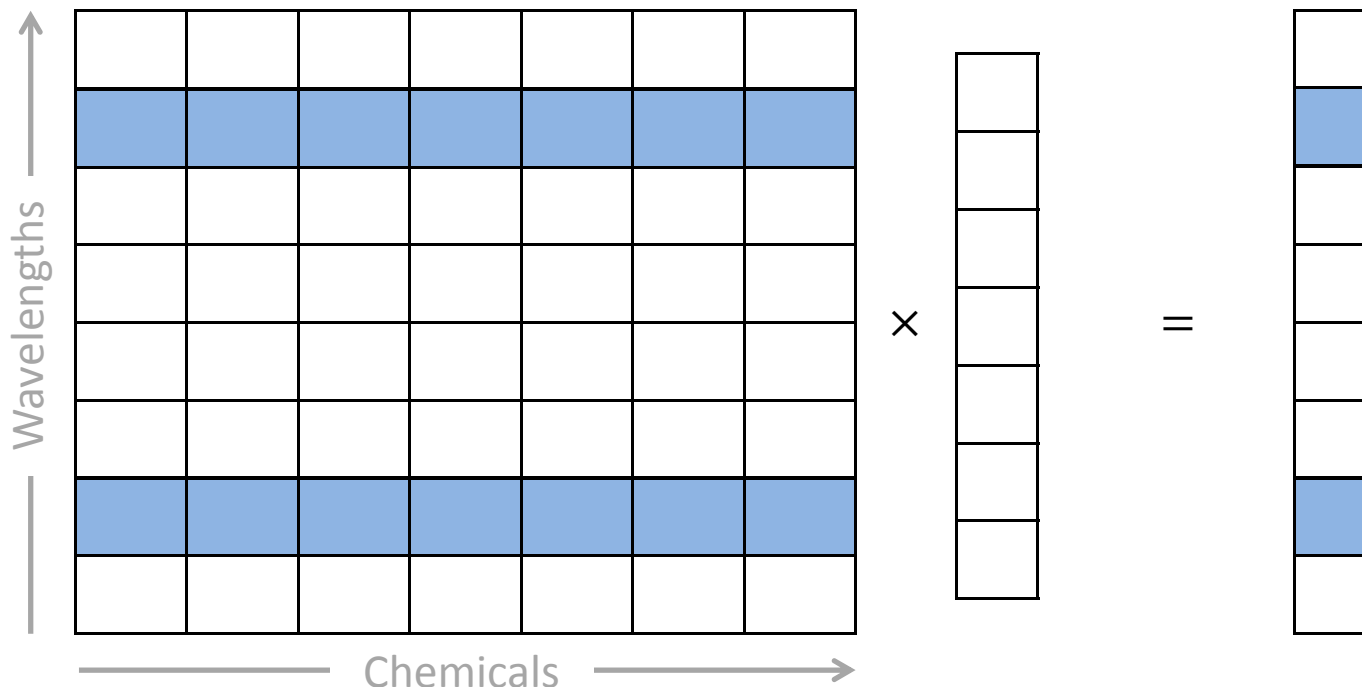
$$s.t.: x \geq 0$$



$A' (2 \times p)$

$x (p \times 1)$

$b' (2 \times 1)$

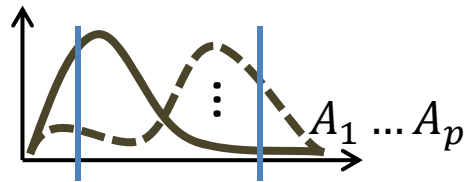




# Active mixture analysis

## Solution

- Assume that  $x$  is sparse

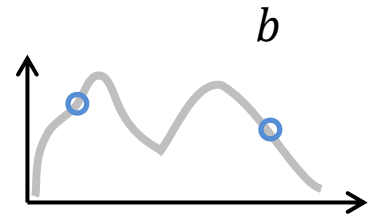


$A' (2 \times p)$

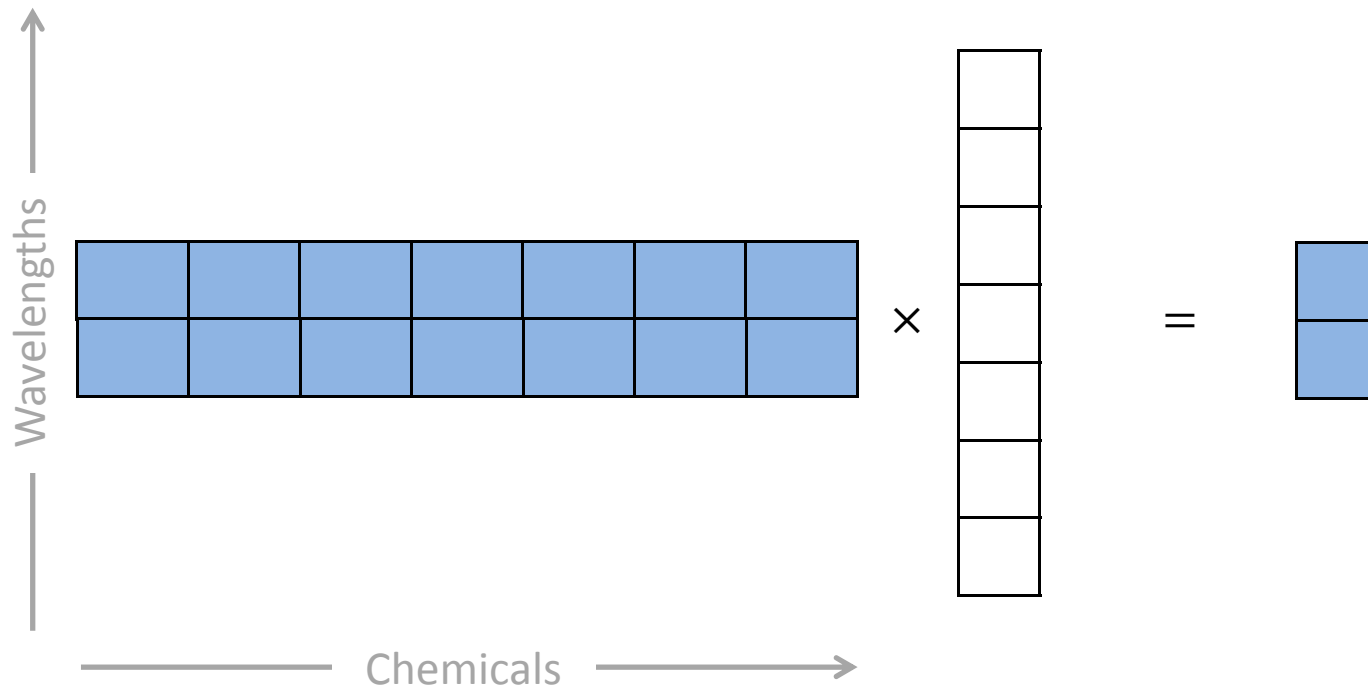
$$A'x = b'$$

$$s.t.: x \geq 0$$

$x (p \times 1)$



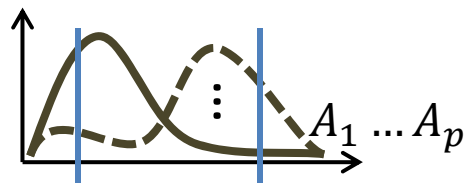
$b' (2 \times 1)$



# Active mixture analysis

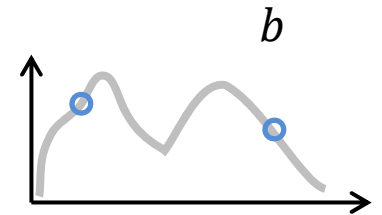
## Subset selection

- Select 1-2 elements in  $x$



$$A'x = b'$$

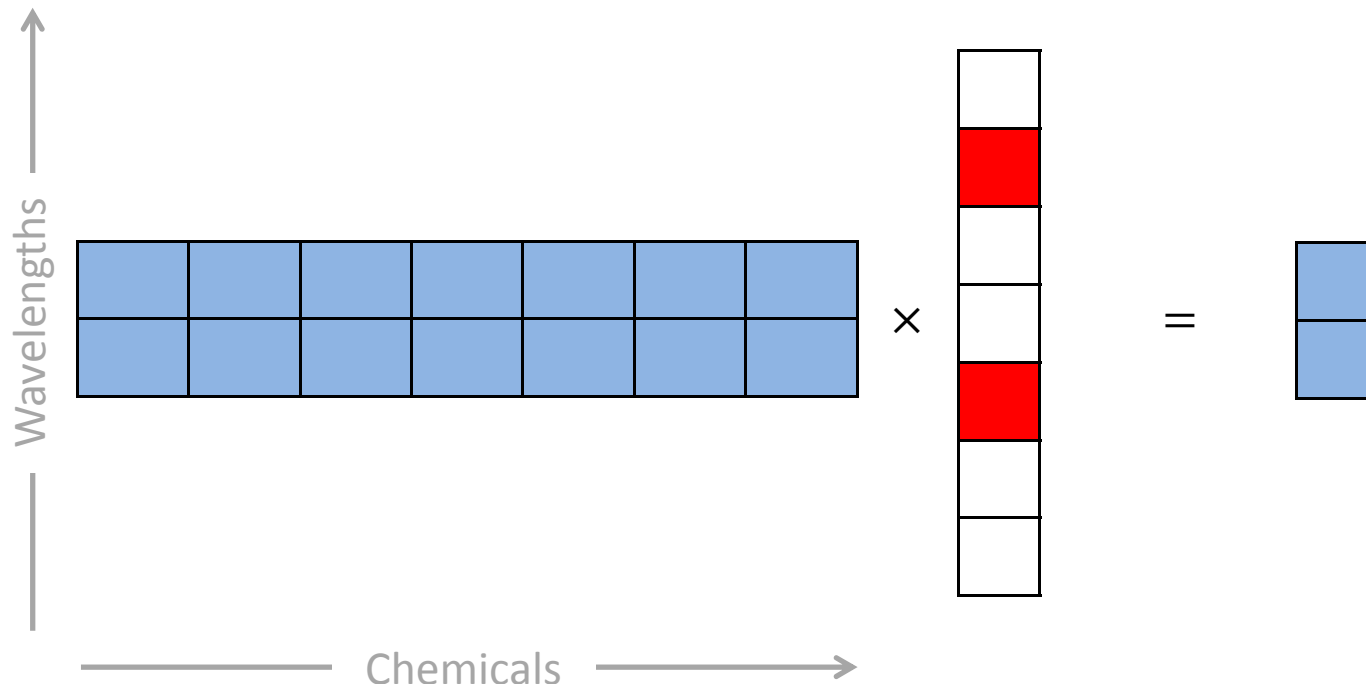
$$s.t.: x \geq 0$$



$A' (2 \times p)$

$x (p \times 1)$

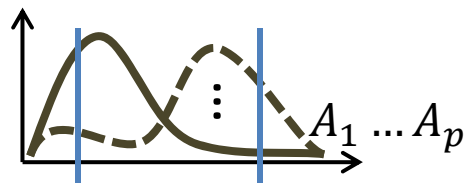
$b' (2 \times 1)$



# Active mixture analysis

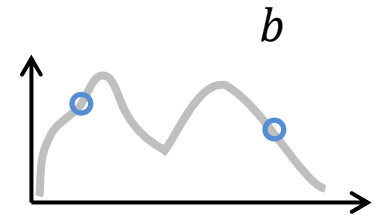
## Interpretation

- One element in  $x$  implies one column in  $A$



$$A'x = b'$$

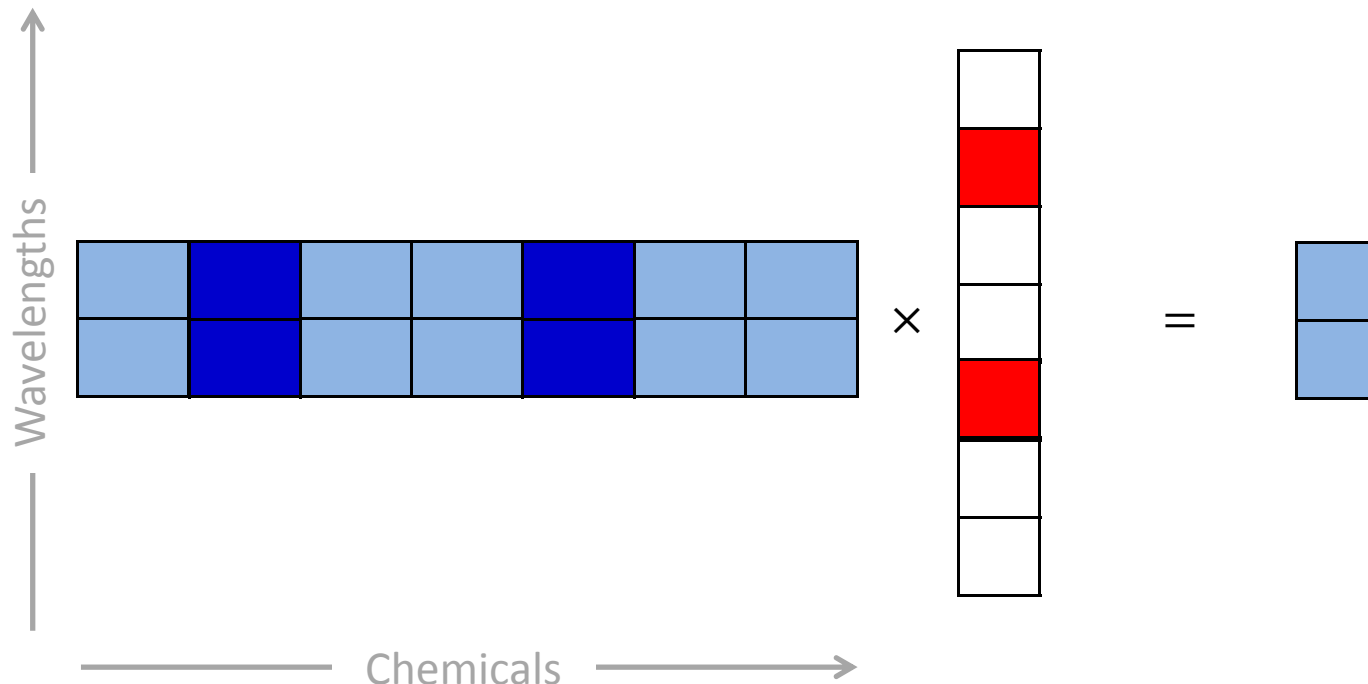
$$s.t.: x \geq 0$$



$A' (2 \times p)$

$x (p \times 1)$

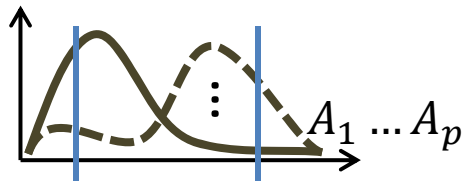
$b' (2 \times 1)$



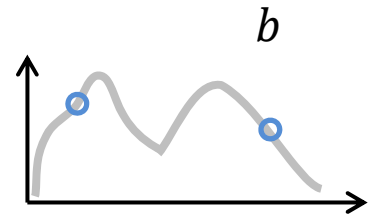
# Active mixture analysis

## The selection is not unique

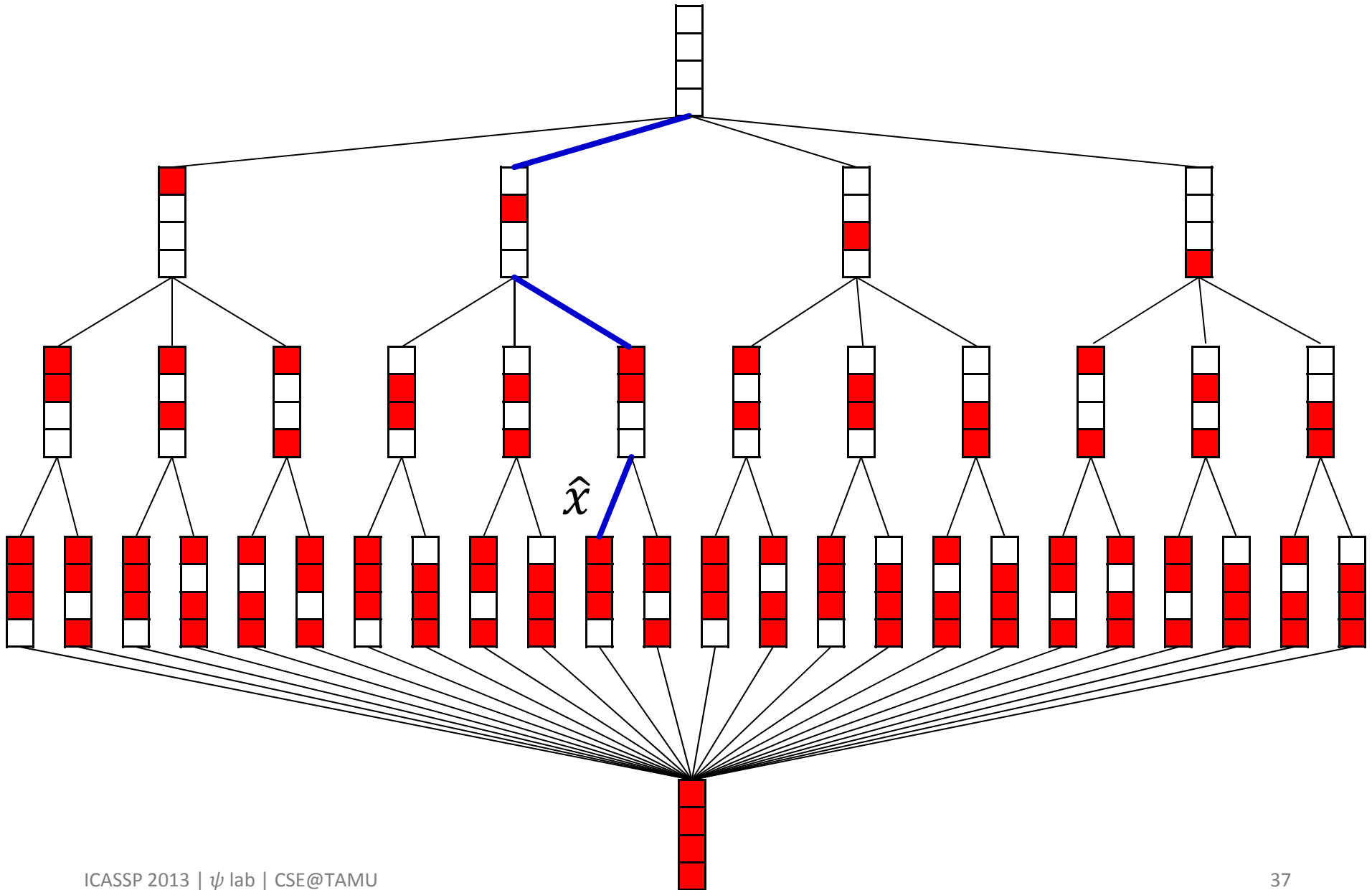
- A combinatorial problem  $\Rightarrow$  search



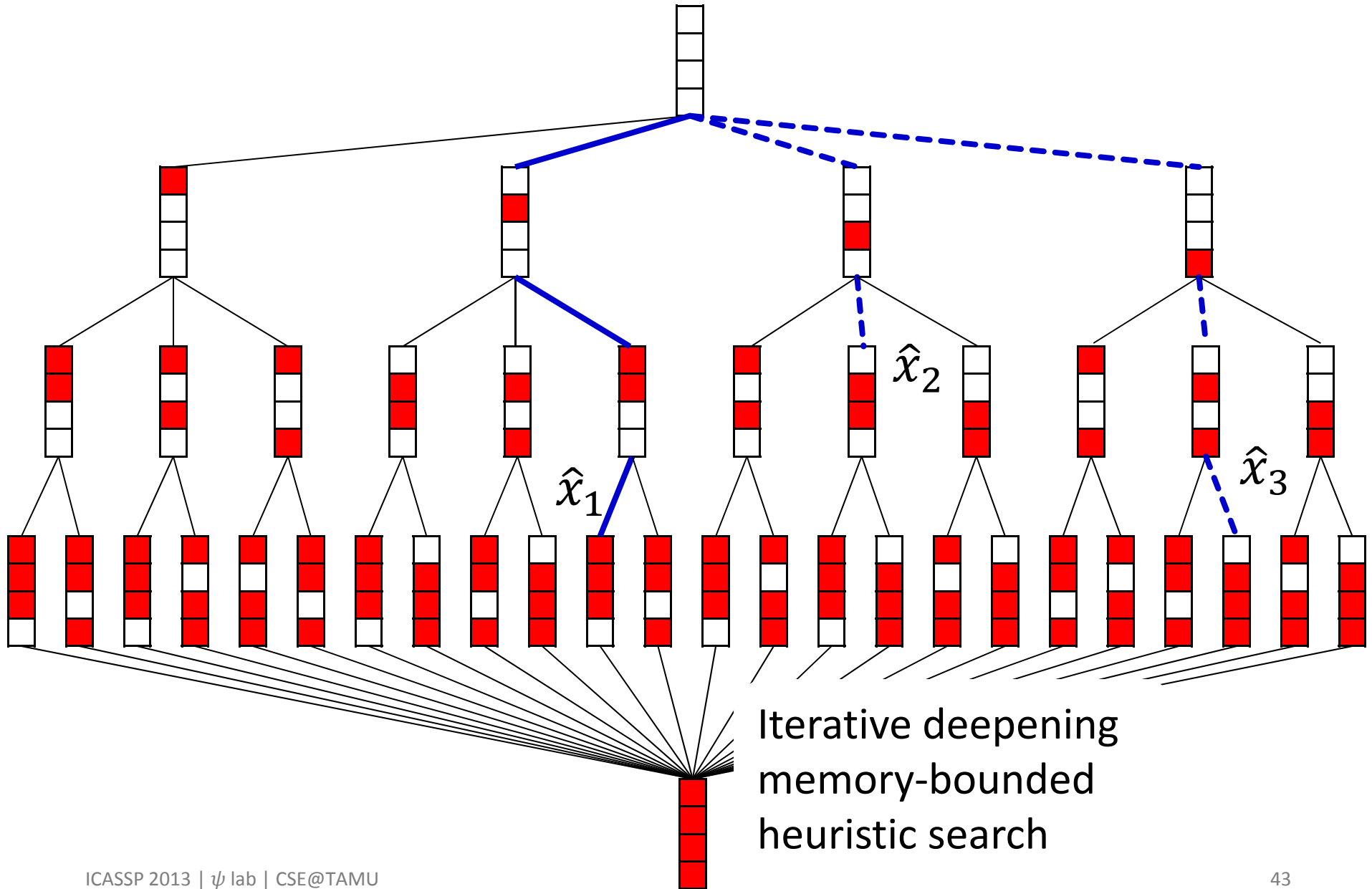
$$A'x = b'$$
$$s.t.: x \geq 0$$



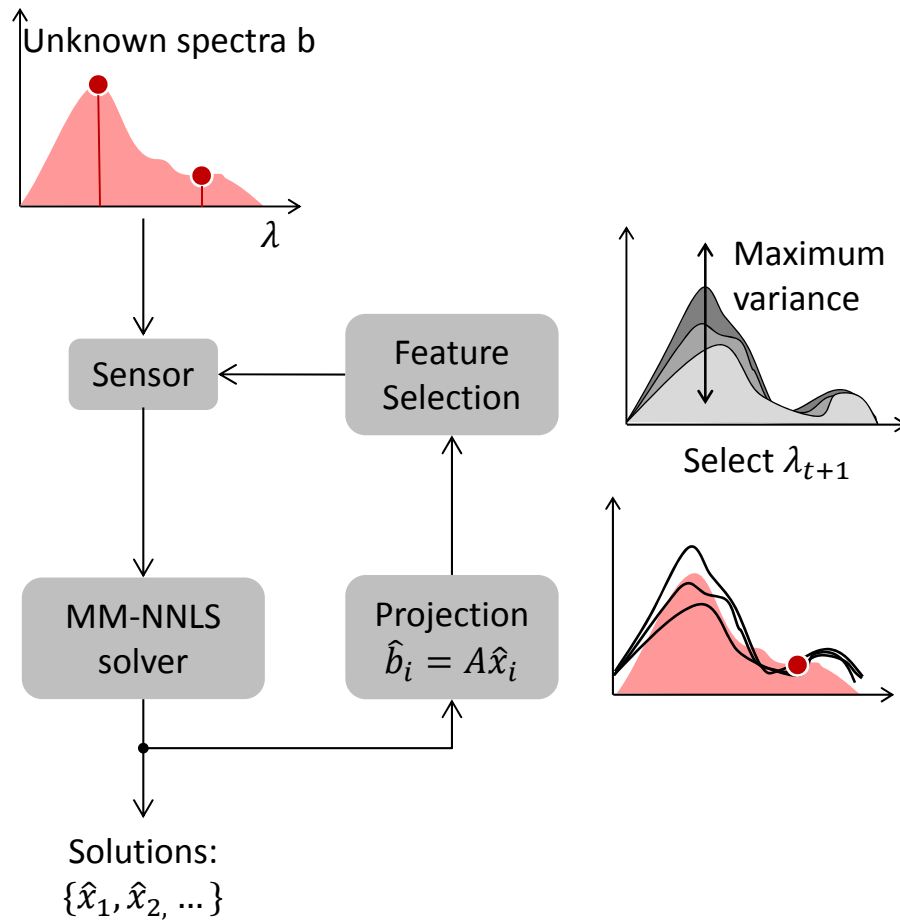
# Unimodal candidate selection



# Multimodal candidate selection



# Wavelength selection



# Case study

## Dataset

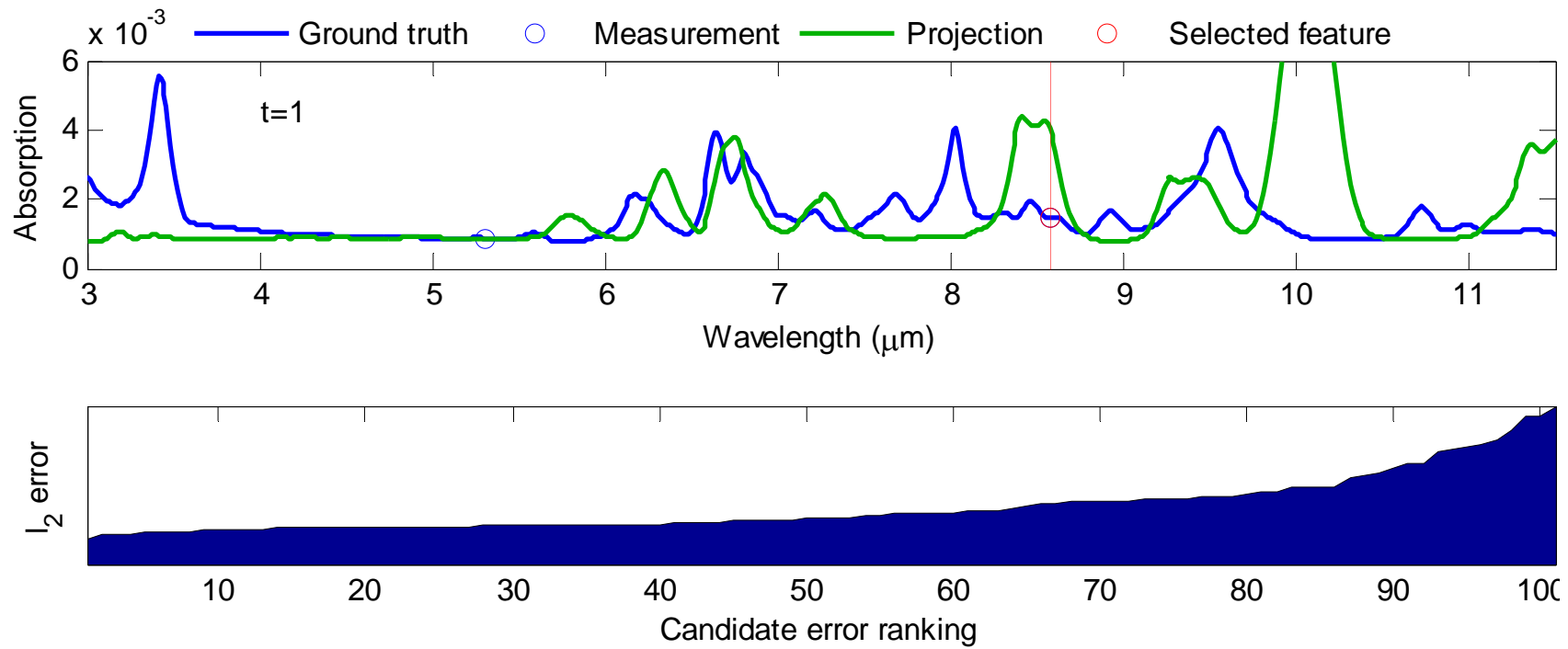
- 100 chemicals from NIST WebBook (randomly chosen)
- Wavelength range: 3 – 11.5 $\mu m$
- Downsampled to 660 spectral lines
- Added 2% Gaussian noise

## Setup

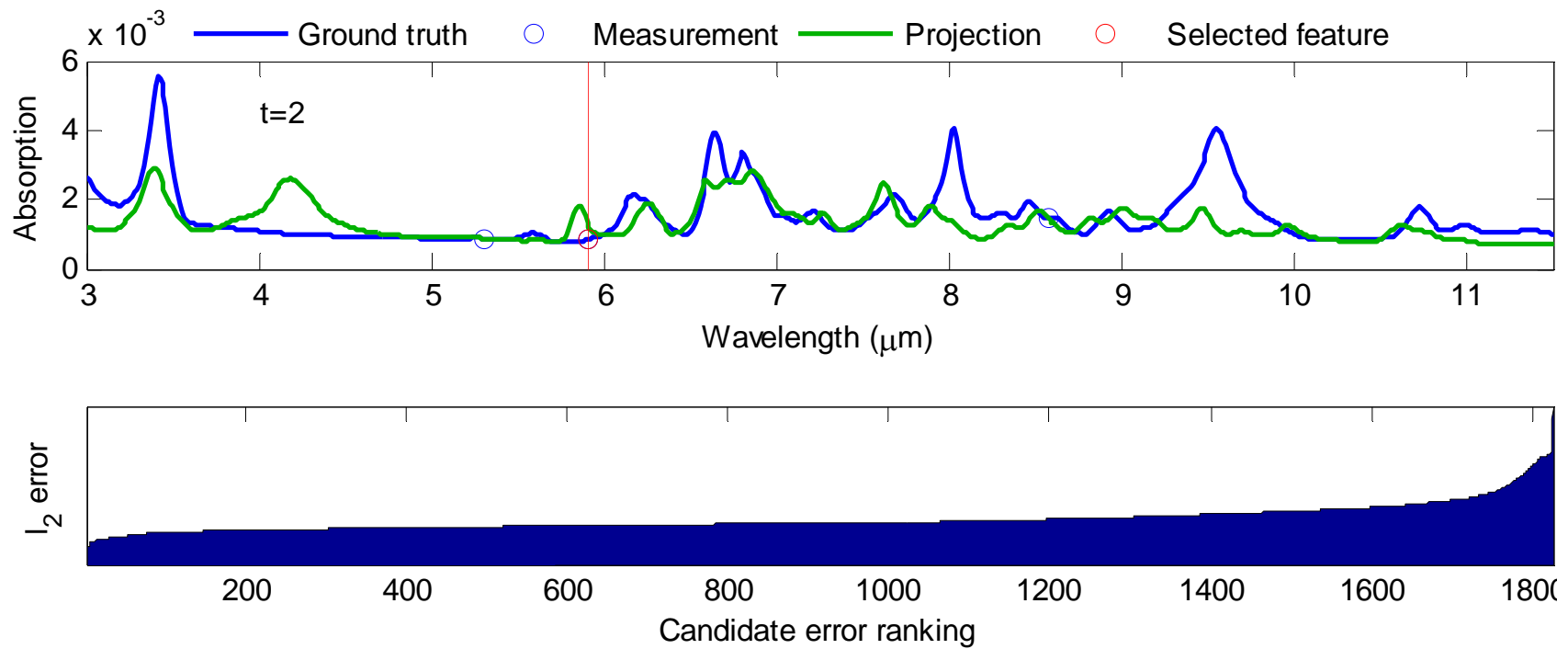
- 3 chemicals mixture (sparsity 3%)
- Search space  $100^3 = 10^6$
- We consider up to  $10^4$  alternate paths



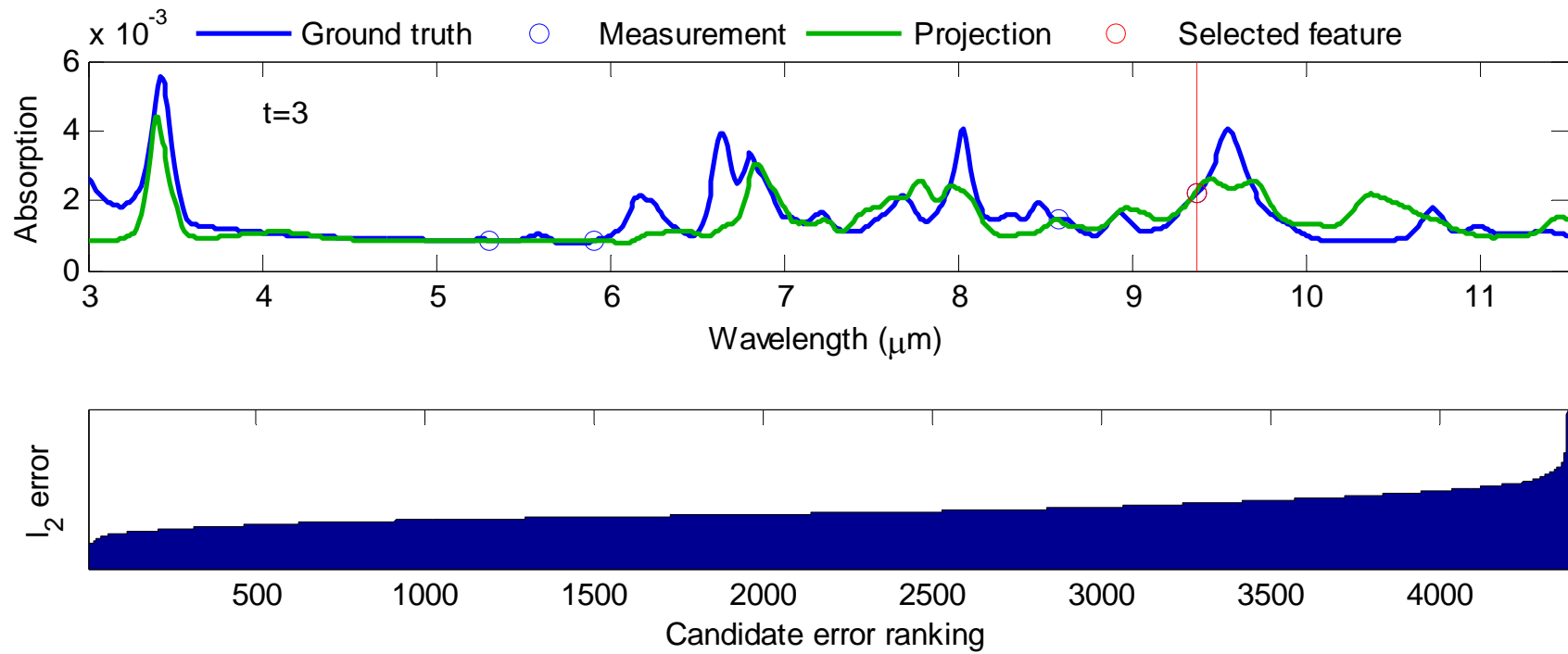
# Step 1



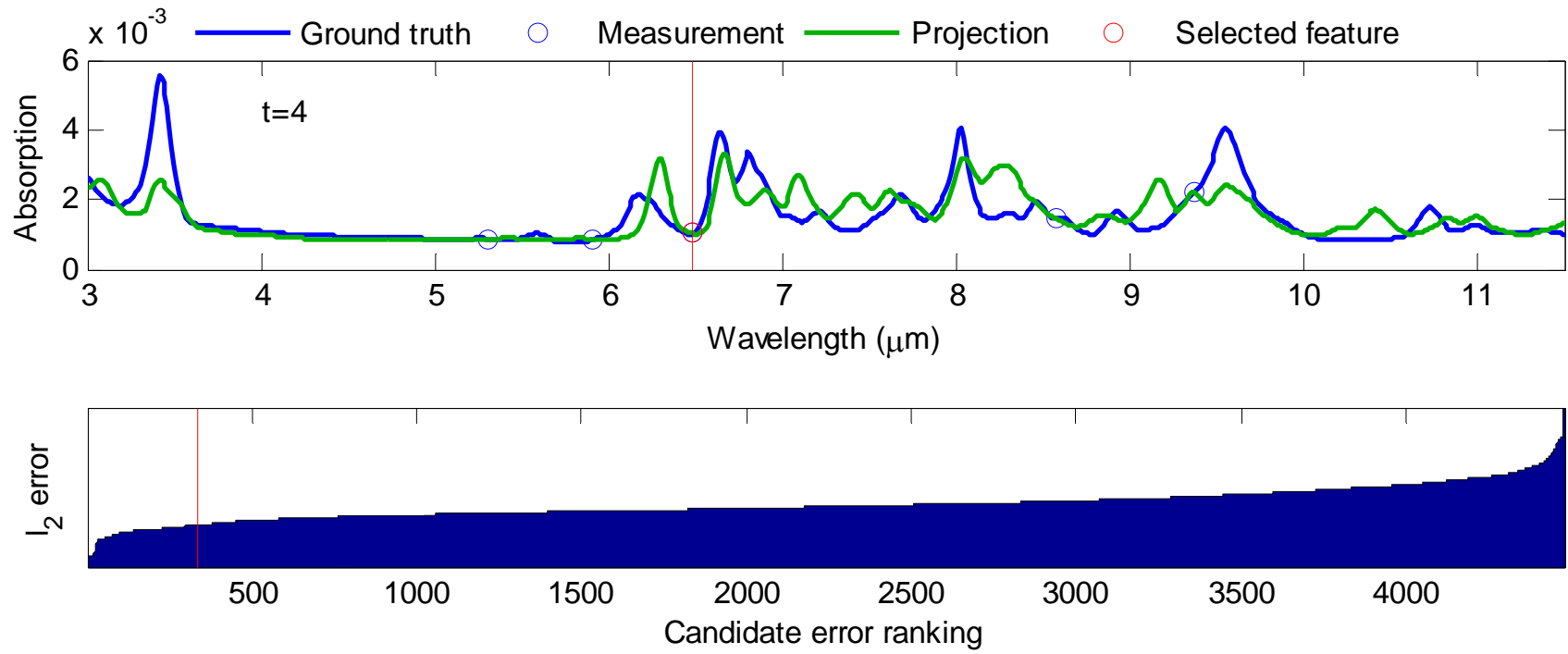
## Step 2



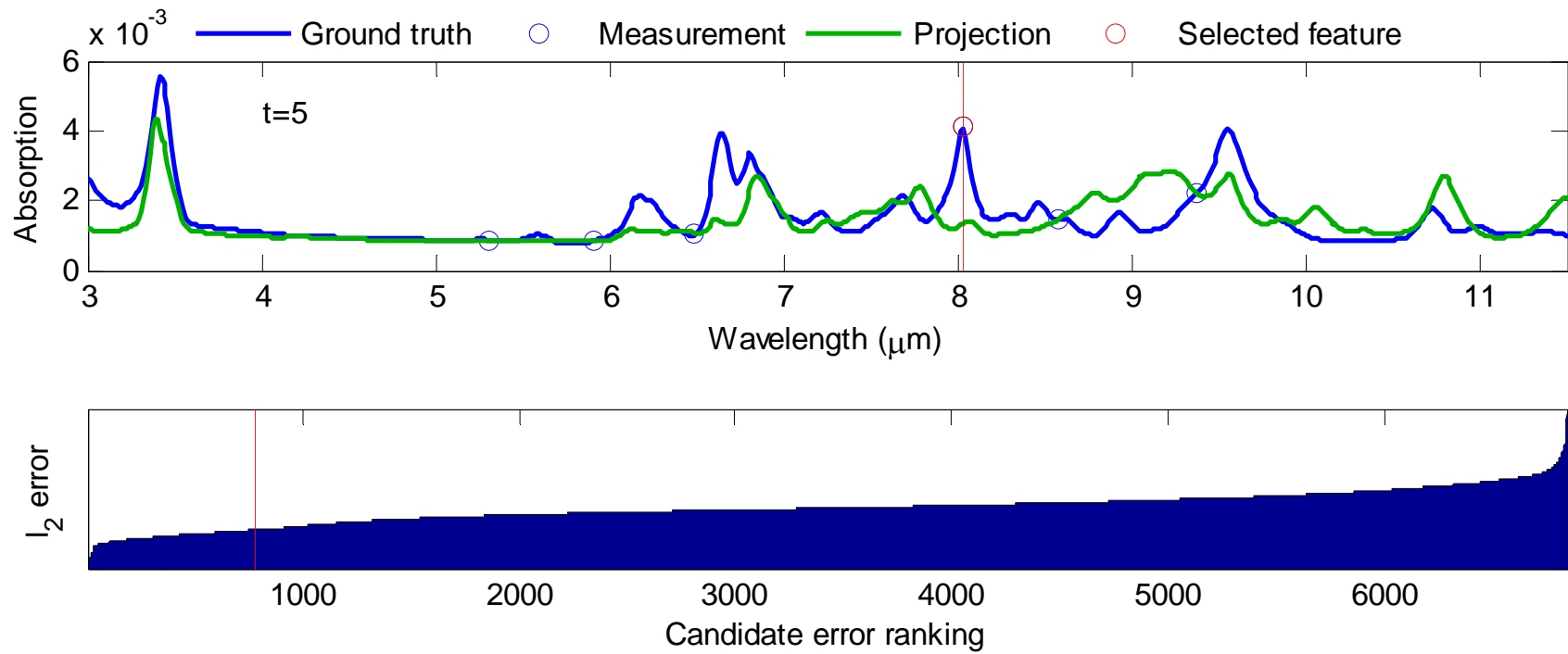
# Step 3



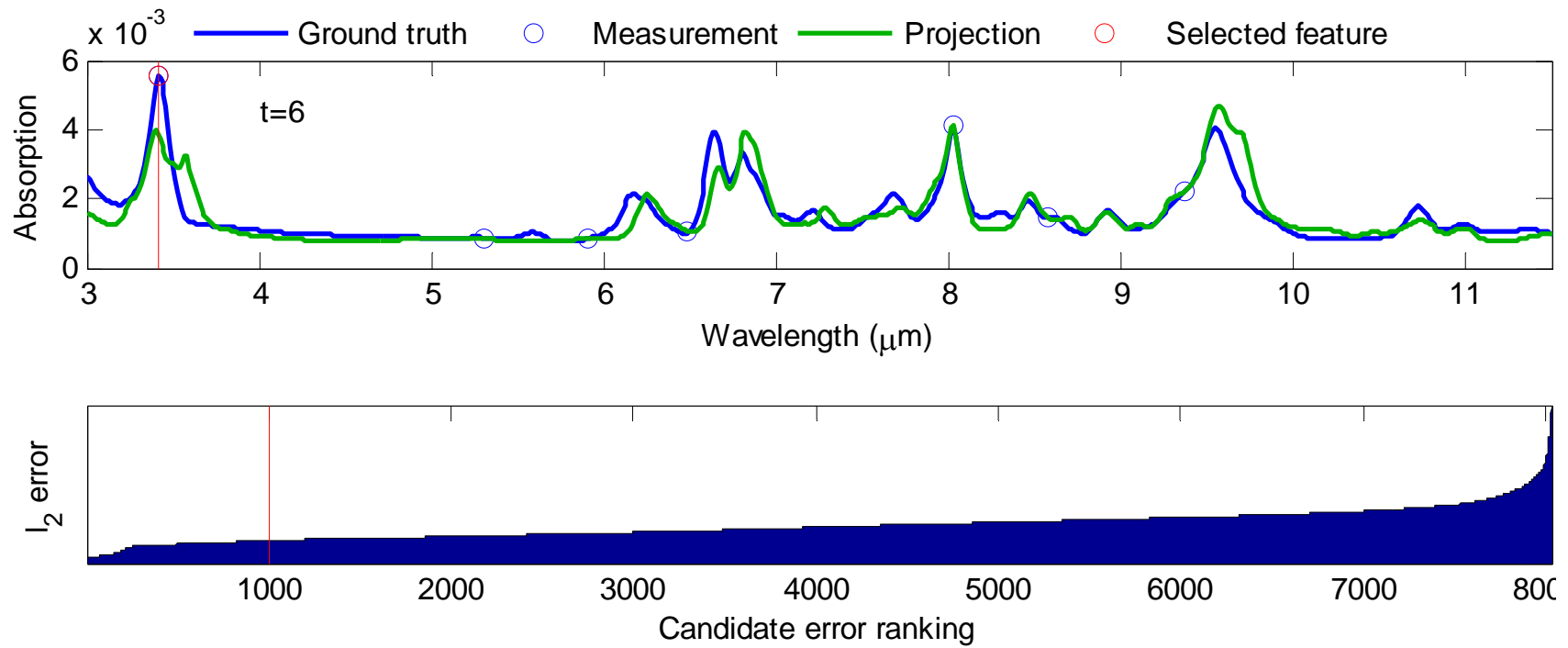
# Step 4



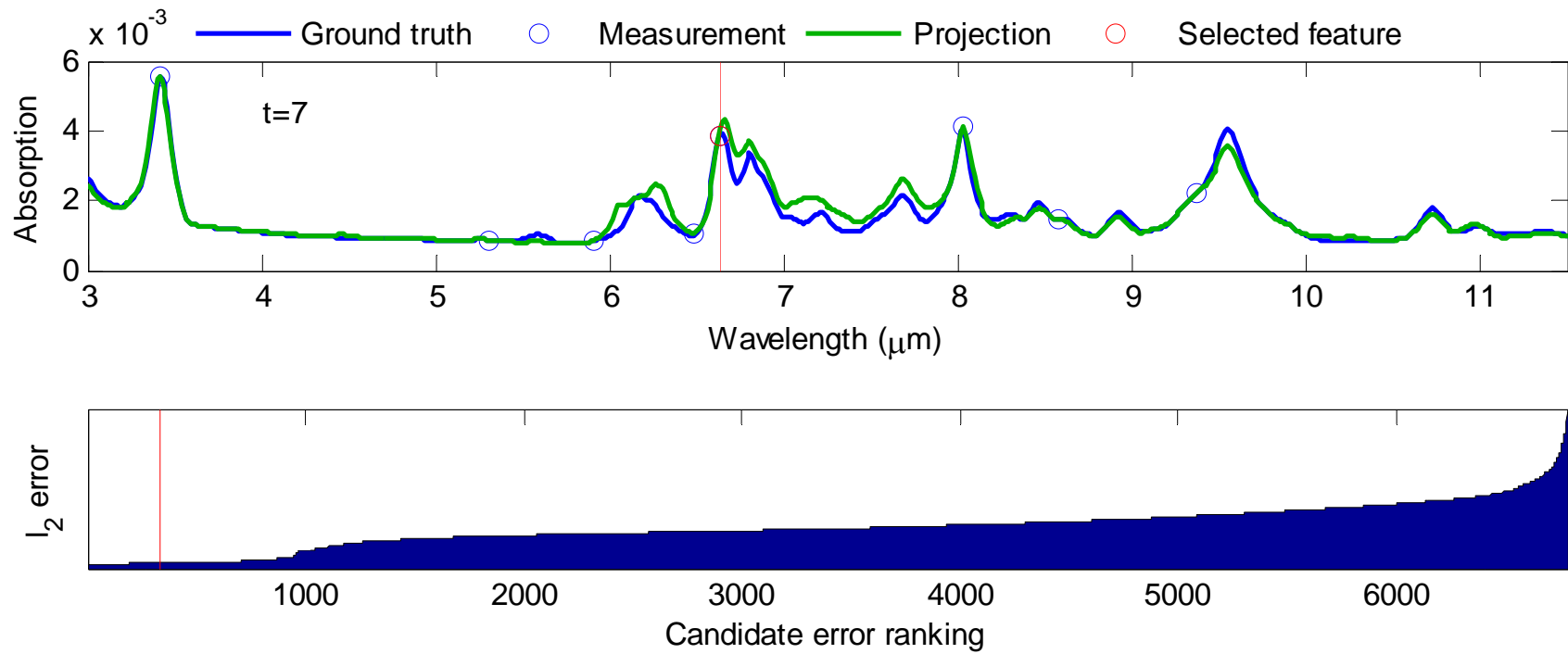
# Step 5



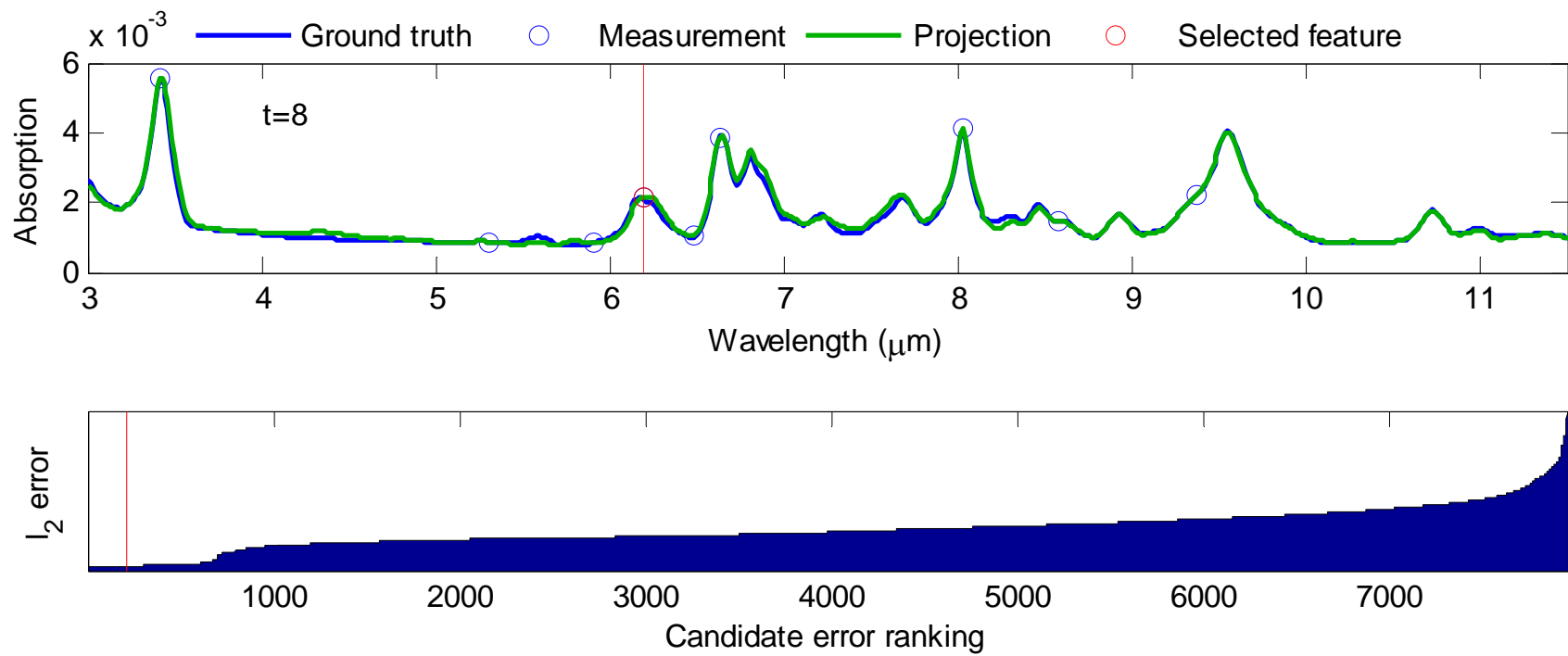
# Step 6



# Step 7

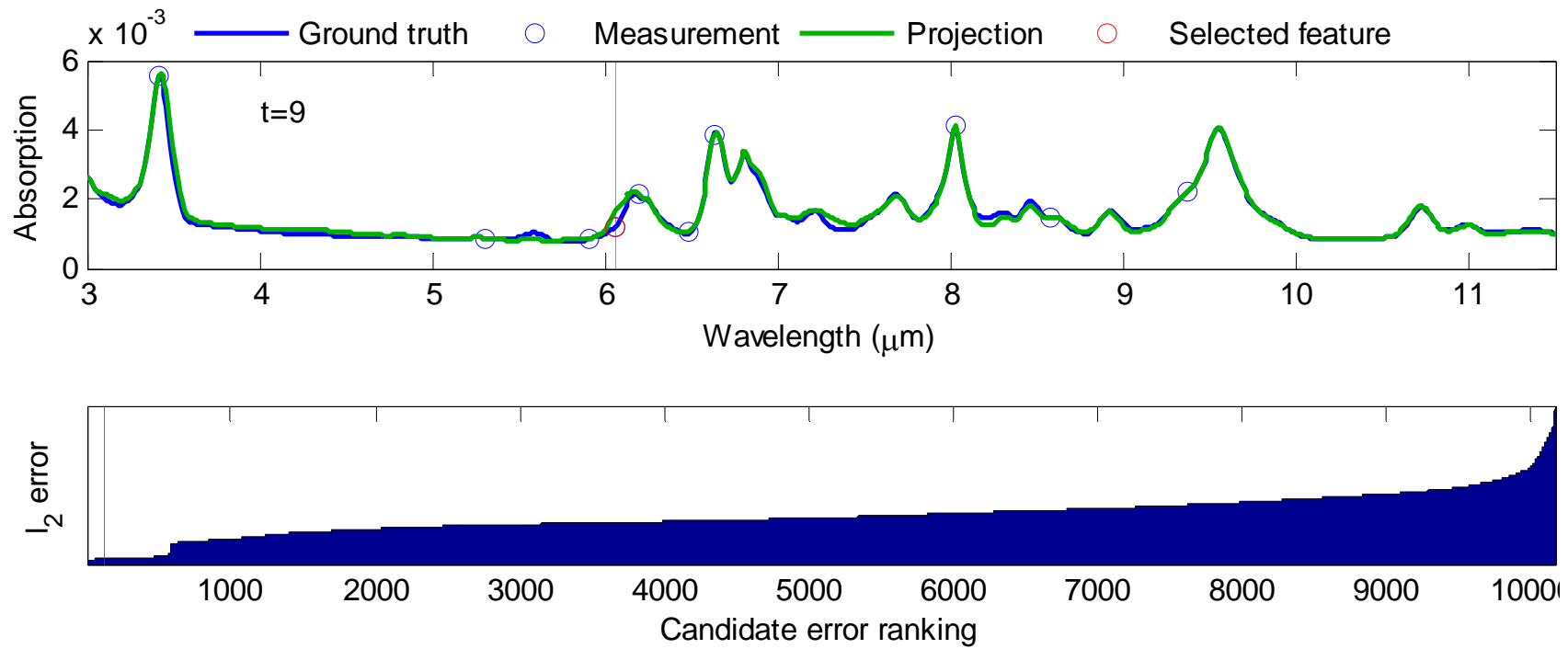


# Step 8

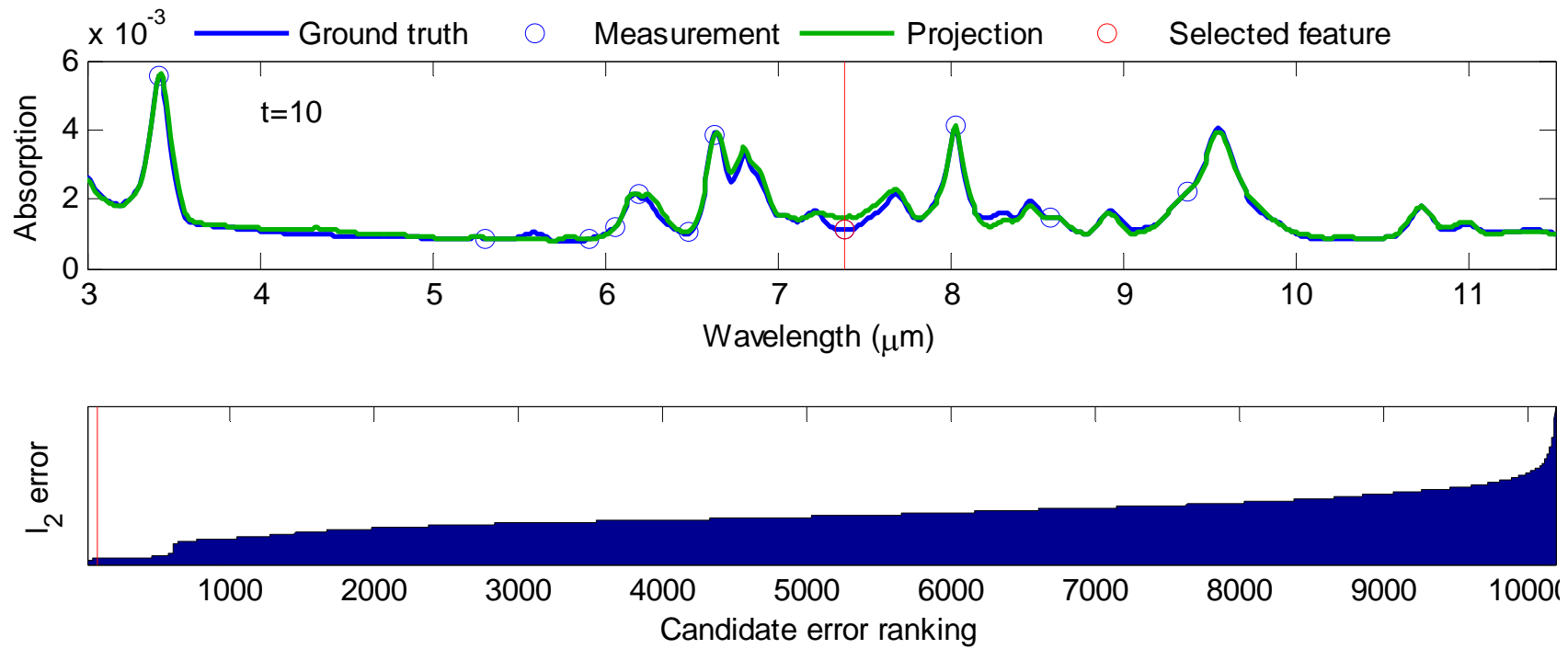




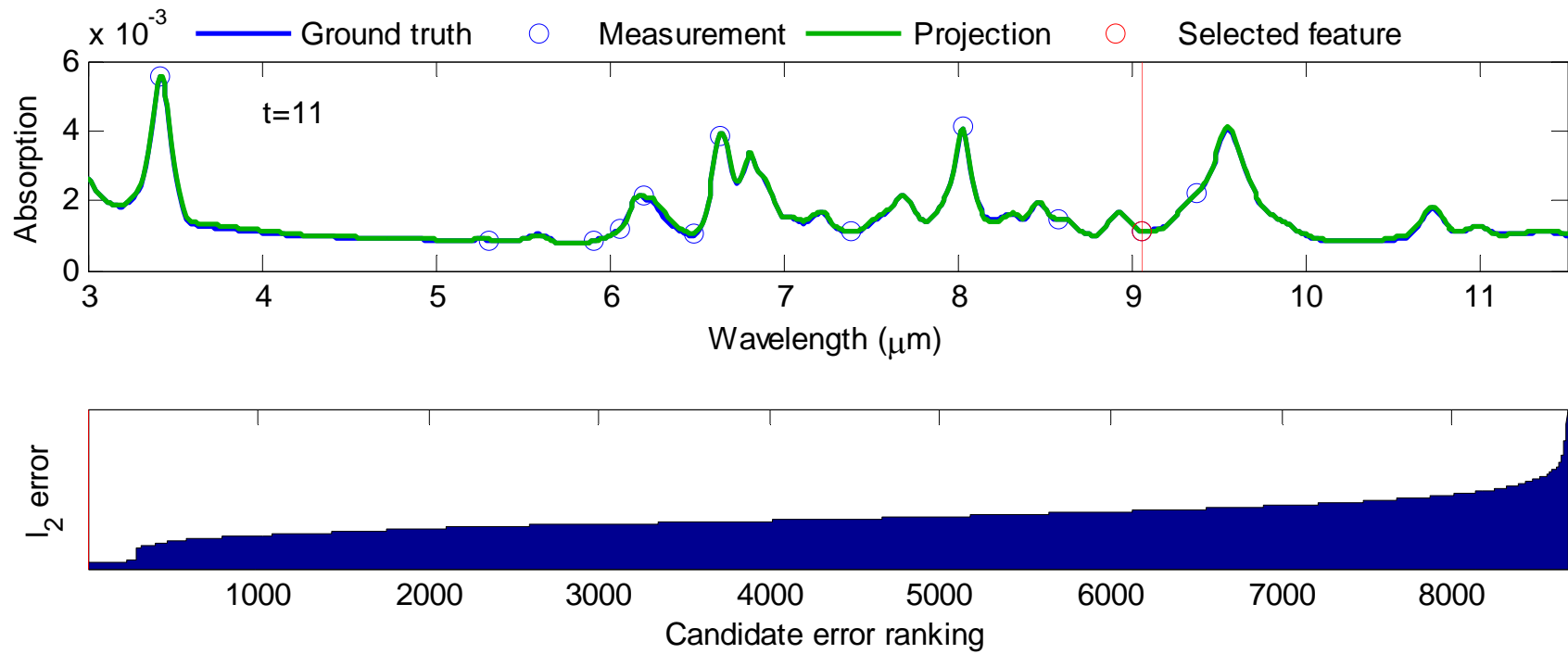
# Step 9



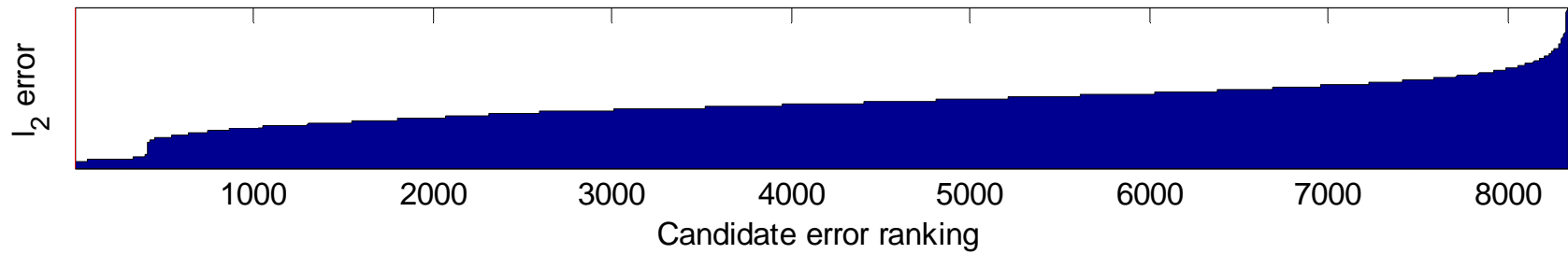
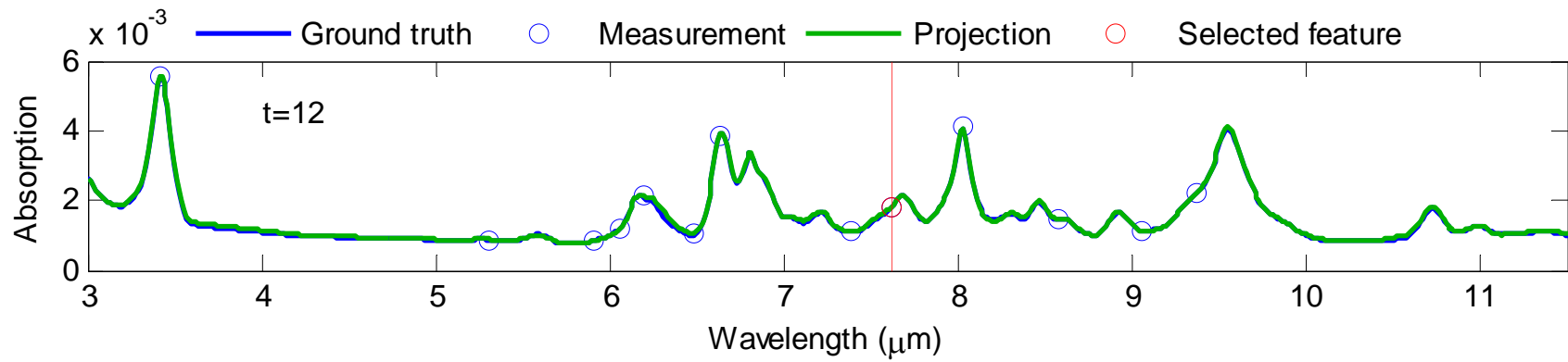
# Step 10



# Step 11



# Step 12



Converged

# Overall performance

## Baseline: passive sensing

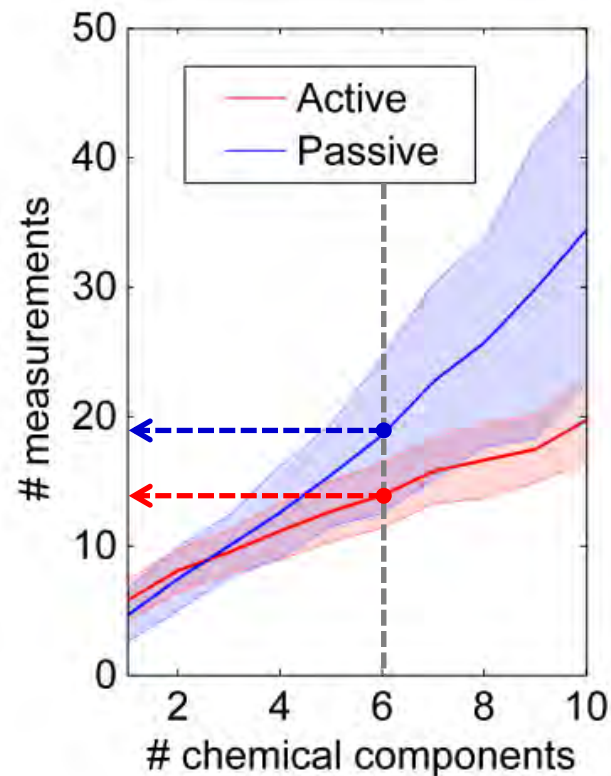
- Sequential forward feature selection
- Trained to distinguish all 100 chemicals
- Generates a fixed sequence of wavelengths

## Experimental protocol

- Randomly pick chemicals and assign random concentrations
  - Concentration has to be significant (larger than 10%)
- Mixtures have from 1 up to 10 chemical components
- Stopping criteria: same  $l_2$  error threshold for both methods

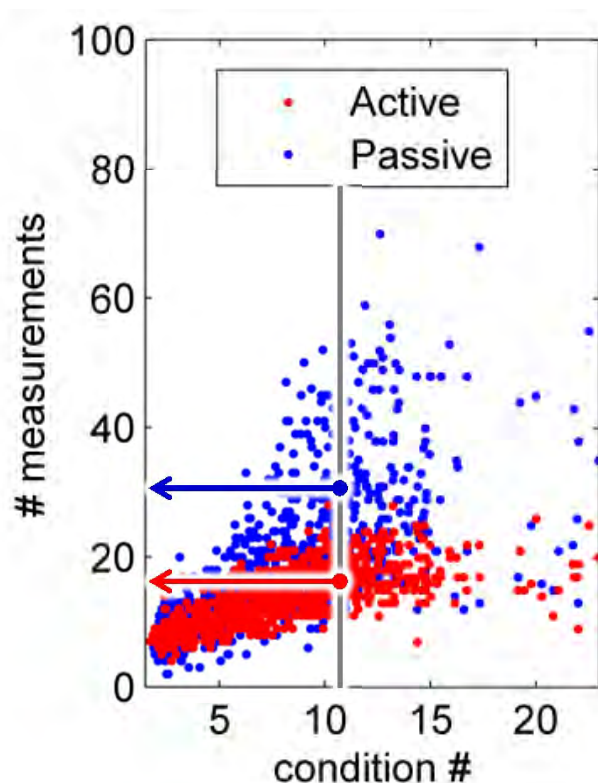
## Number of measurements needed

- Fewer measurements means cost savings
- For each # components we ran 100 examples



## Stability of the solution

- Measured with the condition number of  $A'$ 
  - A measure of correlation among wavenumbers
- Higher condition #  $\Rightarrow$  higher correlation  $\Rightarrow$  less stability



# Discussion and future work

## Discussion

- Multimodal search provides alternative candidates, which help tackle ill-posed problems
- Only a small fraction of candidate solutions are needed to reveal the uncertainty (by virtue of the back-projection)

## Future work

- Experimental validation on real FPI sensor
- Improvements to the algorithm
  - Encouraging diversity to the candidate pool
  - Over-fitting criteria for trace analysis



Thank you  
Questions?