

# Adaptive filtering in the complex wavelet domain with unary filters: application to multiple suppression in geophysics *On echoes and morphing*

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## On echoes and morphing

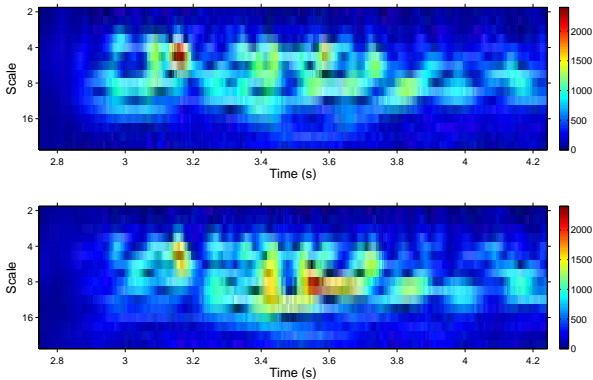


Figure 1: ... and adaptive subtraction

# Agenda

1. Issues in geophysical signal processing
2. Problem: multiple reflections (**echoes**)
  - adaptive filtering with approximate models
3. Complex, continuous wavelets
  - and how they (may) simplify adaptive filtering
4. Discretization, redundancy and unary filters (**morphing**)
  - being practical: back to the discrete world
5. Results
6. Conclusion

## Issues in geophysical signal processing

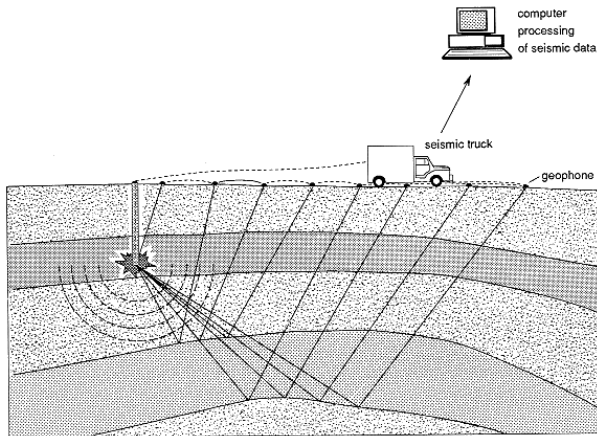


Figure 2: Seismic data acquisition and wave fields.

## Issues in geophysical signal processing

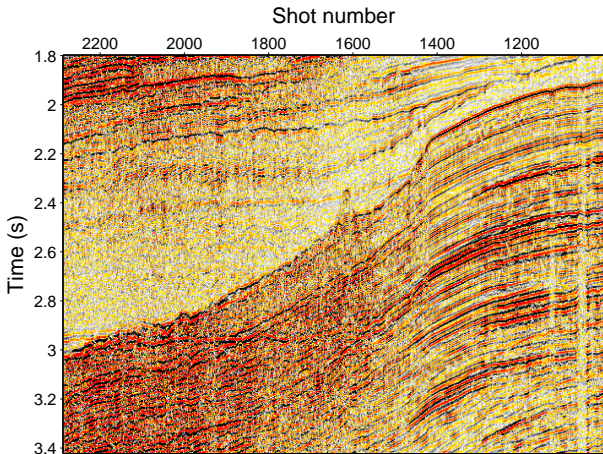


Figure 3: Seismic data: aspect & dimensions (time, offset)

# Issues in geophysical signal processing

## Reflection seismology:

- seismic waves propagate through the subsurface medium
- seismic traces: seismic wave fields recorded at the surface
  - primary reflections: geological interfaces
  - many types of distortions/disturbances
- processing goal: extract relevant information for seismic data
- led to important signal processing tools:
  - $\ell_1$ -promoted deconvolution (Claerbout, 1973)
  - wavelets (Morlet, 1975)
- exabytes ( $10^6$  gigabytes) of incoming data
  - need for fast, scalable algorithms

## Multiple reflections and models

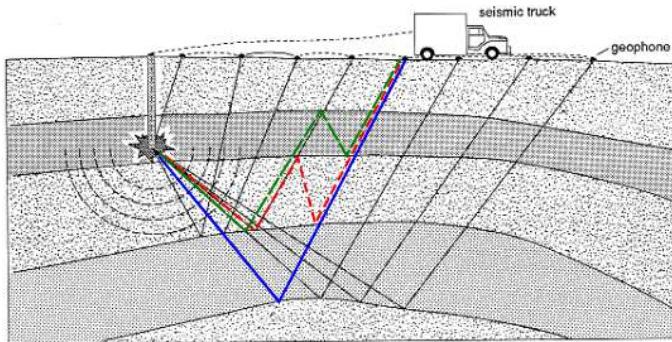


Figure 4: Seismic data acquisition: focus on multiple reflections

## Multiple reflections and models

### Multiple reflections:

- seismic waves bouncing between layers
- one of the most severe types of interferences
- obscure deep reflection layers
- high cross-correlation between primaries ( $p$ ) and multiples ( $m$ )
- additional incoherent noise ( $n$ )
- $d(t) = p(t) + m(t) + n(t)$ 
  - model-based multiple attenuation:  $x_1(t), x_2(t), x_3(t)$
- how to use approximate models?



## Multiple reflections and models

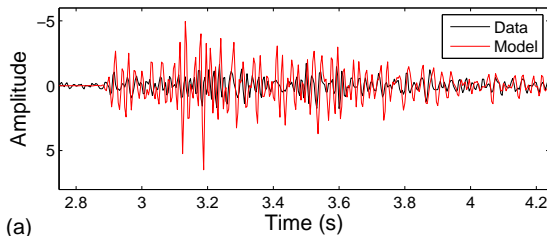


Figure 5: Multiple reflections: data trace  $d$  and model  $x_1$

## Multiple reflections and models

### Multiple filtering:

- multiple prediction (correlation, wave equation) has limitations
- models are not accurate
  - $m(t) \approx a_k(t)x_k(t - \tau_k(t))$ ?
  - standard: identify, apply a matching filter, subtract
- primaries and multiples are not (fully) uncorrelated
  - same (seismic) source
  - similarities/dissimilarities in time
  - similarities/dissimilarities in frequency
- variations in amplitude, waveform, delay
- issues in matching filter length:
  - short filters and windows: local details
  - long filters and windows: large scale effects

## Multiple reflections and models

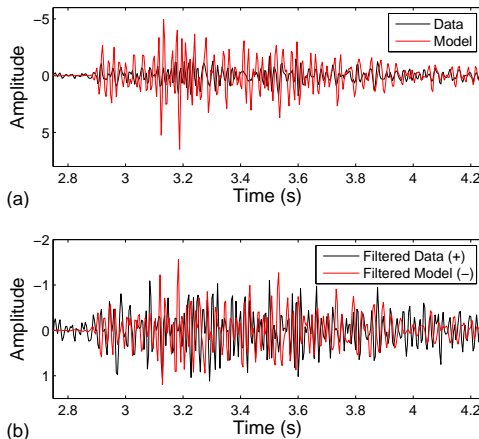


Figure 6: Multiple reflections: data trace, model and adaptation

## Multiple reflections and models

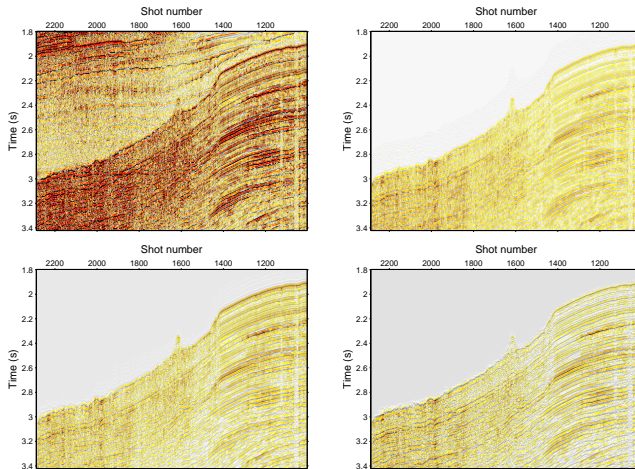


Figure 7: Multiple reflections: data trace and models, 2D version

## Multiple reflections and models

- A long history of multiple filtering methods
  - general idea: combine adaptive filtering and transforms
    - data transforms: Fourier, Radon
    - enhance the differences between primaries, multiples and noise
    - reinforce the adaptive filtering capacity
  - intrication with adaptive filtering?
    - might be complicated (think about inverse transform)
- Main idea here:
  - exploit the non-stationary in the data
  - naturally allow both large scale & local detail matching
  - work in a complex domain: amplitude and phase representation
  - emulate an analytic signal representation (Hilbert transform)

⇒ Complex, continuous wavelets

- intermediate complexity in the transform
- hyper-simplicity in the (unary) adaptive filtering

## Continuous wavelets

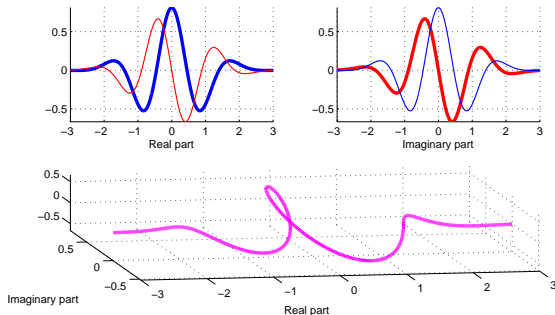


Figure 8: Complex wavelets at two different scales - 1

## Continuous wavelets

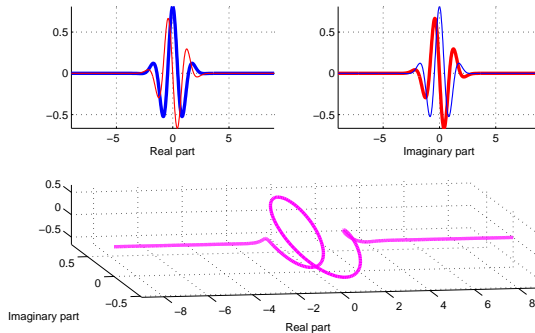


Figure 9: Complex wavelets at two different scales - 2

## Continuous wavelets

- Transformation group:
  - affine = translation ( $\tau$ ) + dilation ( $a$ )
- Basis functions:

$$\psi_{\tau,a}(t) = \frac{1}{\sqrt{a}} \psi\left(\frac{t - \tau}{a}\right)$$

- $a > 1$ : dilation
- $a < 1$ : contraction
- $1/\sqrt{a}$ : energy normalization
- multiresolution (vs monoresolution in STFT)

$$\psi_{\tau,a}(t) \xrightarrow{\text{FT}} \sqrt{a} \Psi(af) e^{-i2\pi f\tau}$$



## Continuous wavelets

- Definition

$$C_s(\tau, a) = \int s(t) \psi_{\tau,a}^*(t) dt$$

- Vector interpretation

$$C_s(\tau, a) = \langle s(t), \psi_{\tau,a}(t) \rangle$$

projection onto time-scale atoms (vs time-frequency)

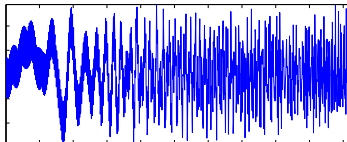
- Redundant transform:  $\tau \rightarrow \tau \times a$  “samples”
- Parseval-like formula

$$C_s(\tau, a) = \langle X(f), \Psi_{\tau,a}(f) \rangle$$

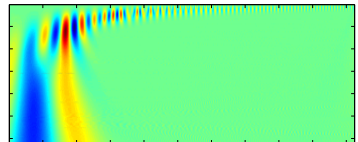
$\Rightarrow$  time-scale domain operations! (cf. Fourier)

# Continuous wavelets

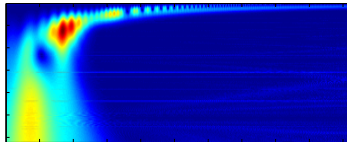
## Introductory example



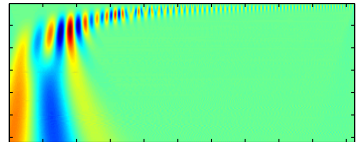
Data



Real part



Modulus



Imaginary part

Figure 10: Noisy chirp mixture in time-scale & sampling

## Continuous wavelets

### Noise spread & feature simplification

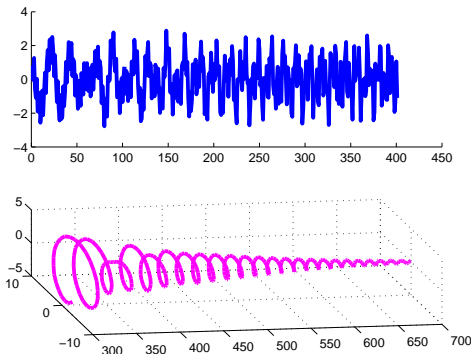


Figure 11: Noisy chirp mixture in time-scale: scale, zoomed wiggle

# Continuous wavelets

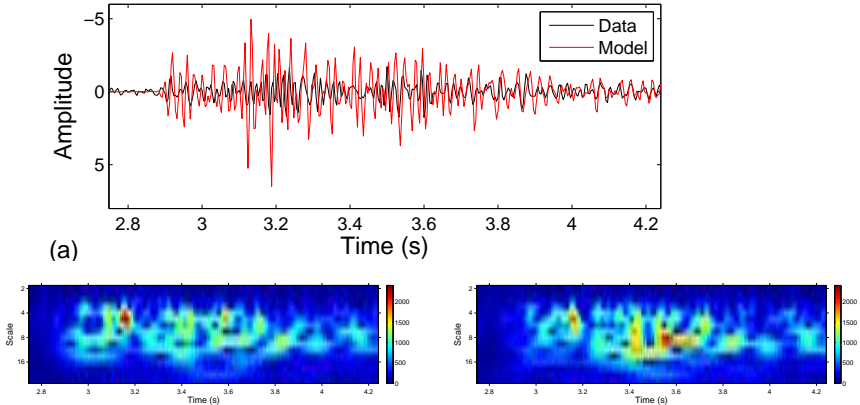


Figure 12: Which morphing is easier: time or time-scale?

## Continuous wavelets

- Inversion with another wavelet  $\phi$

$$s(t) = \iint C_s(u, a) \phi_{u,a}(t) \frac{du da}{a^2}$$

$\Rightarrow$  time-scale domain processing! (back to the signal)

- Scalogram

$$|C_s(t, a)|^2$$

- Energy conversation

$$E = \iint |C_s(t, a)|^2 \frac{dt da}{a^2}$$

- Parseval-like formula

$$\langle s_1, s_2 \rangle = \iint C_{s_1}(t, a) C_{s_2}^*(t, a) \frac{dt da}{a^2}$$

## Continuous wavelets

- Wavelet existence: admissibility criterion

$$0 < A_h = \int_0^{+\infty} \frac{\widehat{\Phi}^*(\nu)\Psi(C)}{\nu} d\nu = \int_{-\infty}^0 \frac{\widehat{\Phi}^*(\nu)\Psi(\nu)}{\nu} d\nu < \infty$$

generally normalized to 1

- Induces band-pass property:
  - necessary condition:  $|\Phi(0)| = 0$ , or zero-average shape
  - amplitude spectrum neglectable w.r.t.  $|v|$  at infinity
- examples: Morlet-Gabor (non. adm.)

$$\psi(t) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{t^2}{2\sigma^2}} e^{-i2\pi f_0 t}$$

## Discretization, redundancy and unary filters

Being practical again: deal with discrete signals

- Can one sample in time-scale (CWT):

$$C_s(\tau, a) = \int s(t) \psi_{\tau,a}^*(t) dt, \quad \psi_{\tau,a}(t) = \frac{1}{\sqrt{a}} \psi\left(\frac{t - \tau}{a}\right)$$

with  $c_{j,k} = C_s(kb_0a_0^j, a_0^j)$ ,  $(j, k) \in \mathbb{Z}$  and still be able to recover  $s(t)$ ?

- Result 1 (Daubechies, 1984): there exists a wavelet frame if  $a_0b_0 < C$ , (depending on  $\psi$ ). A frame is generally redundant
- Result 2 (Meyer, 1985): there exist an orthonormal basis for a specific  $\psi$  (non trivial, Meyer wavelet) and  $a_0 = 2$   $b_0 = 1$

Now: how to choose the practical level of redundancy?

## Discretization, redundancy and unary filters

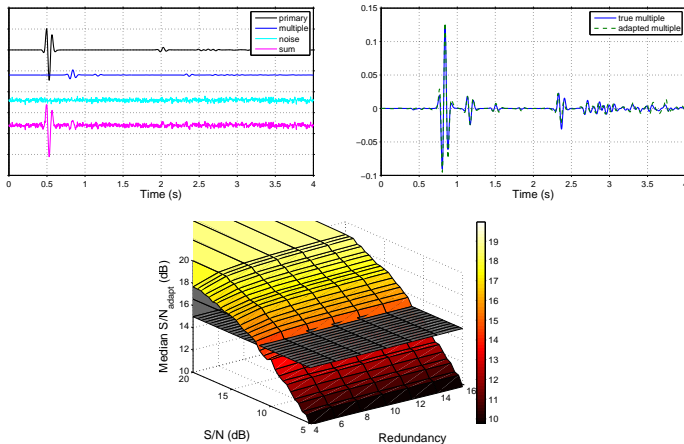


Figure 13: Redundancy selection with variable noise experiments



## Discretization, redundancy and unary filters

- Complex Morlet wavelet:

$$\psi(t) = \pi^{-1/4} e^{-i\omega_0 t} e^{-t^2/2}, \quad \omega_0: \text{central frequency}$$

- Discretized time  $r$ , octave  $j$ , voice  $v$ :

$$\psi_{r,j}^v[n] = \frac{1}{\sqrt{2^{j+v/V}}} \psi\left(\frac{nT - r2^j b_0}{2^{j+v/V}}\right), \quad b_0: \text{sampling at scale zero}$$

- Time-scale analysis:

$$\mathbf{d} = d_{r,j}^v = \langle d[n], \psi_{r,j}^v[n] \rangle = \sum_n d[n] \overline{\psi_{r,j}^v[n]}$$

## Discretization, redundancy and unary filters

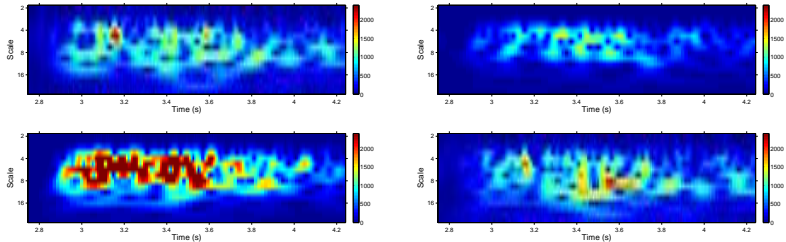


Figure 14: Morlet wavelet scalograms, data and models

Take advantage from the closest similarity/dissimilarity:

- remember the wiggle: on sliding windows, at each scale, a single complex coefficient compensates amplitude and phase

## Discretization, redundancy and unary filters

- Windowed adaptation: complex  $\mathbf{a}_{\text{opt}}$  compensates local delay/amplitude mismatches:

$$\mathbf{a}_{\text{opt}} = \arg \min_{\{a_k\}(k \in K)} \left\| \mathbf{d} - \sum_k a_k \mathbf{x}_k \right\|^2$$

- Vector Wiener equations for complex signals:

$$\langle \mathbf{d}, \mathbf{x}_m \rangle = \sum_k a_k \langle \mathbf{x}_k, \mathbf{x}_m \rangle$$

- Time-scale synthesis:

$$\hat{d}[n] = \sum_r \sum_{j,v} \hat{d}_{r,j}^v \tilde{\psi}_{r,j}^v[n]$$

# Results

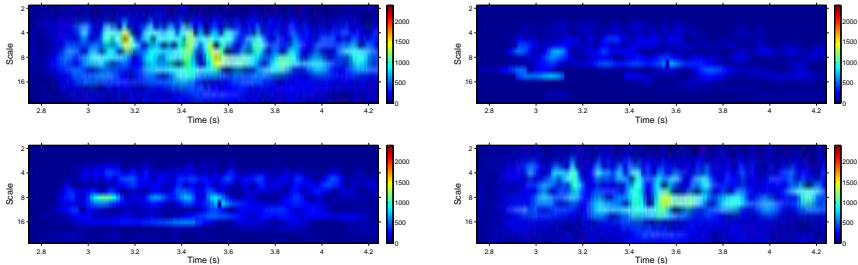


Figure 15: Wavelet scalograms, data and models, after unary adaptation

## Results (reminders)

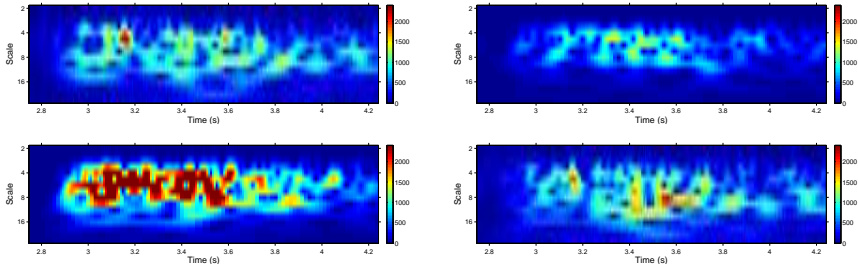


Figure 16: Wavelet scalograms, data and models

## Results

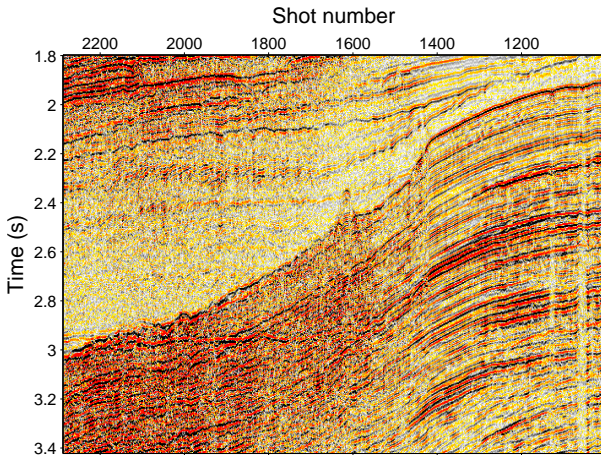


Figure 17: Original data

# Results

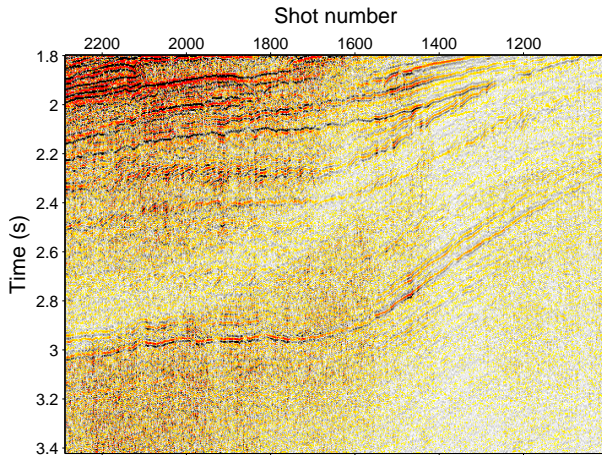


Figure 18: Filtered data

# Conclusions

## Take-away messages:

- Technical side
  - Take good care of cascaded processing
  - Non-stationary, wavelet-based, adaptive multiple filtering
  - “Complex” wavelet transform + simple one-tap (unary) filter
  - Redundancy selection: noise robustness and processing speed
  - Smooth adaptation to adaptive joint multiple model filtering
- Practical side
  - Industrial integration
  - Competitive with more standard processing
  - Alternative results: less sensitive to random noises
- Future work: better integrate incoherent noise



## Acknowledgements & references



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